# 14. Instability of Superposed Fluids



Figure 14.1: Wind over water: A layer of fluid of density  $\rho^+$  moving with relative velocity V over a layer of fluid of density  $\rho^-$ .

**Define interface**:  $h(x, y, z) = z - \eta(x, y) = 0$  so that  $\nabla h = (-\eta_x, -\eta_y, 1)$ . The unit normal is given by

$$\hat{\boldsymbol{n}} = \frac{\boldsymbol{\nabla}h}{|\boldsymbol{\nabla}h|} = \frac{(-\eta_x, -\eta_y, 1)}{\left(\eta_x^2 + \eta_y^2 + 1\right)^{1/2}}$$
(14.1)

Describe the fluid as inviscid and irrotational, as is generally appropriate at high  $\mathcal{R}e$ . Basic state:  $\eta = 0$ ,  $\boldsymbol{u} = \boldsymbol{\nabla}\phi$ ,  $\phi = \pm \frac{1}{2}V_x$  for  $z\pm$ . Perturbed state:  $\phi = \pm \frac{1}{2}V_x + \phi_{\pm}$  in  $z\pm$ , where  $\phi_{\pm}$  is the perturbation field. Solve

$$\boldsymbol{\nabla} \cdot \boldsymbol{u} = \nabla^2 \phi_{\pm} = 0 \tag{14.2}$$

subject to BCs:

- 1.  $\phi_{\pm} \to 0$  as  $z \to \pm \infty$
- 2. Kinematic BC:  $\frac{\partial \eta}{\partial t} = u \cdot n$ , where

$$\boldsymbol{u} = \boldsymbol{\nabla} \left( \mp \frac{1}{2} V_x + \phi_{\pm} \right) = \mp \frac{1}{2} V \hat{\boldsymbol{x}} + \frac{\partial \phi_{\pm}}{\partial x} \hat{\boldsymbol{x}} + \frac{\partial \phi_{\pm}}{\partial y} \hat{\boldsymbol{y}} + \frac{\partial \phi_{\pm}}{\partial z} \hat{\boldsymbol{z}}$$
(14.3)

from which

$$\frac{\partial \eta}{\partial t} = \left(\mp \frac{1}{2}V + \frac{\partial \phi_{\pm}}{\partial x}\right)(-\eta_x) + \frac{\partial \phi_{\pm}}{\partial y}(-\eta_y) + \frac{\partial \phi_{\pm}}{\partial z}$$
(14.4)

**Linearize**: assume perturbation fields  $\eta$ ,  $\phi_{\pm}$  and their derivatives are small and therefore can neglect their products.

Thus 
$$\hat{\eta} \approx (-\eta_x, -\eta_y, 1)$$
 and  $\frac{\partial \eta}{\partial t} = \pm \frac{1}{2} V \eta_x + \frac{\partial \phi_{\pm}}{\partial z} \Rightarrow$   
$$\frac{\partial \phi_{\pm}}{\partial z} = \frac{\partial \eta}{\partial t} \mp \frac{1}{2} V \frac{\partial \eta}{\partial x} \quad on \ z = 0$$
(14.5)

3. Normal Stress Balance:  $p_- - p_+ = \sigma \nabla \cdot \mathbf{n}$  on  $z = \eta$ . Linearize:  $p_- - p_+ = -\sigma (\eta_{xx} + \eta_{yy})$  on z = 0. We now deduce  $p_\pm$  from time-dependent Bernoulli:

$$\rho \frac{\partial \phi}{\partial t} + \frac{1}{2}\rho u^2 + p + \rho gz = f(t)$$
(14.6)

where  $u^2 = \frac{1}{4}V^2 \mp V \frac{\partial \phi_{\pm}}{\partial x} + H.O.T.$ Linearize:

$$\rho_{\pm}\frac{\partial\phi_{\pm}}{\partial t} + \frac{1}{2}\rho_{\pm}\left(\mp V\frac{\partial\phi_{\pm}}{\partial x}\right) + p_{\pm} + \rho_{\pm}g\eta = G(t)$$
(14.7)

 $\mathbf{SO}$ 

$$p_{-} - p_{+} = (\rho_{+} - \rho_{-})g\eta + (\rho_{+}\frac{\partial\phi_{\pm}}{\partial t} - \rho_{-}\frac{\partial\phi_{-}}{\partial t}) + \frac{V}{2}(\rho_{-}\frac{\partial\phi_{-}}{\partial x} + \rho_{+}\frac{\partial\phi_{+}}{\partial x}) = -\sigma(\eta_{xx} + \eta_{yy})$$
(14.8)

is the linearized normal stress BC. Seek normal mode (wave) solutions of the form

$$\eta = \eta_0 e^{i\alpha x + i\beta y + \omega t} \tag{14.9}$$

$$\phi_{\pm} = \phi_{0\pm} e^{\pm kz} e^{i\alpha x + i\beta y + \omega t} \tag{14.10}$$

where  $\nabla^2 \phi_{\pm} = 0$  requires  $k^2 = \alpha^2 + \beta^2$ . Apply kinematic BC:  $\frac{\partial \phi_{\pm}}{\partial z} = \frac{\partial \eta}{\partial t} \mp \frac{1}{2} V \frac{\partial \eta}{\partial x}$  at  $z = 0 \Rightarrow$ 

$$\mp k\phi_{0\pm} = \omega\eta_0 \mp \frac{1}{2}i\alpha V\eta_0 \tag{14.11}$$

Normal stress BC:

$$k^{2}\sigma\eta_{0} = -g(\rho_{-} - \rho_{+})\eta_{0} + \omega(\rho_{+}\phi_{0+} - \rho_{-}\phi_{0-}) + \frac{1}{2}i\alpha V\left(\rho_{+}\phi_{0+} + \rho_{-}\phi_{0-}\right)$$
(14.12)

Substitute for  $\phi_{0\pm}$  from (14.11):

$$-k^{3}\sigma = \omega \left[\rho_{+}(\omega - \frac{1}{2}i\alpha V) + \rho_{-}(\omega + \frac{1}{2}i\alpha V)\right] + gk(\rho_{-} - \rho_{+}) + \frac{1}{2}i\alpha V \left[\rho_{+}(\omega - \frac{1}{2}i\alpha V) + \rho_{-}(\omega + \frac{1}{2}i\alpha V)\right]$$

 $\mathbf{SO}$ 

$$\omega^{2} + i\alpha V\left(\frac{\rho_{-} - \rho_{+}}{\rho_{-} + \rho_{+}}\right)\omega - \frac{1}{4}\alpha^{2}V^{2} + k^{2}C_{0}^{2} = 0$$
(14.13)

where  $C_0^2 \equiv \left(\frac{\rho - -\rho_+}{\rho_- + \rho_+}\right) \frac{g}{k} + \frac{\sigma}{\rho_- + \rho_+} k$ . **Dispersion relation:** we now have the relation between  $\omega$  and k

$$\omega = \frac{1}{2}i\left(\frac{\rho_{+} - \rho_{-}}{\rho_{-} + \rho_{+}}\right)\mathbf{k}\cdot\mathbf{V} \pm \left[\frac{\rho_{-}\rho_{+}}{(\rho_{-} + \rho_{+})^{2}}\left(\mathbf{k}\cdot\mathbf{V}\right)^{2} - k^{2}C_{0}^{2}\right]^{1/2}$$
(14.14)

where  $\mathbf{k} = (\alpha, \beta), k^2 = \alpha^2 + \beta^2$ . The system is UNSTABLE if  $\mathcal{R}e(\omega) > 0$ , i.e. if

$$\frac{\rho_{+}\rho_{-}}{\rho_{-}+\rho_{+}}\left(\boldsymbol{k}\cdot\boldsymbol{V}\right)^{2} > k^{2}C_{0}^{2}$$
(14.15)

#### Squires Theorem:

Disturbances with wave vector  $\mathbf{k} = (\alpha, \beta)$  parallel to  $\mathbf{V}$  are most unstable. This is a general property of shear flows.

We proceed by considering two important special cases, Rayleigh-Taylor and Kelvin-Helmholtz instability.

## 14.1 Rayleigh-Taylor Instability

We consider an initially static system in which heavy fluid overlies light fluid:  $\rho_+ > \rho_-$ , V = 0. Via (14.15), the system is unstable if

$$C_0^2 = \frac{\rho_- - \rho_+}{\rho_+ \rho_-} \frac{g}{k} + \frac{\sigma}{\rho_- + \rho_+} k < 0$$
(14.16)

i.e. if  $\rho_+ - \rho_- > \frac{\sigma k^2}{g} = \frac{4\pi^2 \sigma}{g\lambda^2}$ .

Thus, for instability, we require:  $\lambda > 2\pi\lambda_c$  where  $\lambda_c = \sqrt{\frac{\sigma}{\Delta\rho g}}$  is the capillary length.

#### Heuristic Argument:

Change in Surface Energy:  $\Delta E_S = \sigma \cdot \underbrace{\Delta l}_{arc\ length} = \sigma \left[ \int_0^\lambda ds - \lambda \right] = \frac{1}{4} \sigma \epsilon^2 k^2 \lambda.$ Change in gravitational potential energy:  $\Delta E_G = \int_0^\lambda -\frac{1}{2} \rho g \left( h^2 - h_0^2 \right) dx = -\frac{1}{4} \rho g \epsilon^2 \lambda.$ When is the total energy decreased? When  $\Delta E_{total} = \Delta E_S + \Delta E_G < 0$ , i.e. when  $\rho g > \sigma k^2$ , so  $\lambda > 2\pi l_c$ . The system is thus unstable to long  $\lambda$ . Note:

- 1. The system is stabilized to small  $\lambda$  disturbances by  $\sigma$
- 2. The system is always unstable for suff. large  $\lambda$
- 3. In a finite container with width smaller than  $2\pi\lambda_c$ , the system may be stabilized by  $\sigma$ .
- 4. System may be stabilized by temperature gradients since Marangoni flow acts to resist surface deformation. E.g. a fluid layer on the ceiling may be stabilized by heating the ceiling.



Figure 14.2: The base state and the perturbed state of the Rayleigh-Taylor system, heavy fluid over light.



Figure 14.3: Rayleigh-Taylor instability may be stabilized by a vertical temperature gradient.

### 14.2 Kelvin-Helmholtz Instability

We consider shear-driven instability of a gravitationally stable base state. Specifically,  $\rho_{-} \ge \rho_{+}$  so the system is gravitationally stable, but destabilized by the shear.

Take **k** parallel to **V**, so  $(\mathbf{V} \cdot \mathbf{k})^2 = k^2 V^2$  and the instability criterion becomes:

$$\rho_{-}\rho_{+}V^{2} > (\rho_{-} - \rho_{+})\frac{g}{k} + \sigma k \qquad (14.17)$$

Equivalently,

$$\rho_{-}\rho_{+}V^{2} > (\rho_{-} - \rho_{+})g\frac{\lambda}{2\pi} + \sigma\frac{2\pi}{\lambda}$$
(14.18)

Note:

- 1. System stabilized to short  $\lambda$  disturbances by surface tension and to long  $\lambda$  by gravity.
- 2. For any given  $\lambda$  (or k), one can find a critical V that destabilizes the system.

#### Marginal Stability Curve:

$$V(k) = \left(\frac{\rho_{-} - \rho_{+}}{\rho_{-} \rho_{+}} \frac{g}{k} + \frac{1}{\rho_{-} \rho_{+}} \sigma k\right)^{1/2}$$
(14.19)

V(k) has a minimum where  $\frac{dV}{dk} = 0$ , i.e.  $\frac{d}{dk}V^2 = 0$ .

This implies  $-\frac{\Delta \rho}{k^2} + \sigma = 0 \Rightarrow k_c = \sqrt{\frac{\Delta \rho g}{\sigma}} = \frac{1}{l_{cap}}$ .

The corresponding  $V_c = V(k_c) = \frac{2}{\rho - \rho_+} \sqrt{\Delta \rho g \sigma}$  is the minimal speed necessary for waves.

**E.g.** Air blowing over water: (cgs)  $V_c^2 = \frac{2}{1.2 \cdot 10^{-3}} \sqrt{1 \cdot 10^3 \cdot 70} \Rightarrow V_c \sim 650 \text{cm/s}$  is the minimum wind speed required to generate waves.

These waves have wavenumber  $k_c = \sqrt{\frac{1 \cdot 10^3}{70}} \approx 3.8 \ cm^{-1}$ , so  $\lambda_c = 1.6$  cm. They thus correspond to capillary waves.



Figure 14.4: Kelvin-Helmholtz instability: a gravitationally stable base state is destabilized by shear.



Figure 14.5: Fluid speed V(k) required for the growth of a wave with wavenumber k.

357 Interfacial Phenomena Fall 2010

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.