## 18.03SC Unit 2 Exam

**1.** (a) For what value of *k* is the system represented by  $\ddot{x} + \dot{x} + kx = 0$  critically damped? [8]

(b) For *k* greater than that value, is the system overdamped or underdamped? [4]

(c) Suppose a solution of  $\ddot{x} + \dot{x} + kx = 0$  vanishes at t = 1, and then again for t = 2 (but [8] not in between). What is k?

**2.** (a) Find a solution of  $\ddot{x} + x = 5te^{2t}$ .

(b) Suppose that y(t) is a solution of the same equation,  $\ddot{x} + x = 5te^{2t}$ , such that y(0) = 1 [10] and  $\dot{y}(0) = 2$ . (This is probably *not* the solution you found in (a).) Use y(t) and other functions to write down a solution x(t) such that x(0) = 3 and  $\dot{x}(0) = 5$ .

[10]

**3.** (a) Consider the equation  $\ddot{x} + b\dot{x} + kx = \cos(\omega t)$ . We will vary the spring constant but [10] keep *b* fixed. For what value of *k* is the amplitude of the sinusoidal solution of  $\ddot{x} + b\dot{x} + kx = \cos(\omega t)$  maximal? (Your answer will be a function of  $\omega$  and may depend upon *b* as well.)

**(b)** (Unrelated to the above.) Find the general solution of  $\frac{d^3x}{dt^3} - \frac{dx}{dt} = 0.$  [10]

**4.** A certain system has input signal *y* and system response *x* related by the differential equation  $\ddot{x} + \dot{x} + 6x = 6y$ . It is subjected to a sinusoidal input signal.

(a) Calculate the complex gain  $H(\omega)$ .

[10]

**(b)** Compute the gain at  $\omega = 2$ .

[5]

(c) Compute the phase lag at  $\omega = 2$ .

[5]

**5.** Suppose that  $\frac{1}{2}t\sin(2t)$  is a solution to a certain equation  $m\ddot{x} + b\dot{x} + kx = 4\cos(2t)$ .

(a) Write down a solution to 
$$m\ddot{x} + b\dot{x} + kx = 4\cos(2t-1)$$
. [4]

(b) Write down a solution to  $m\ddot{x} + b\dot{x} + kx = 8\cos(2t)$ .

(c) Determine *m*, *b*, and *k*.

[12]

[4]

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