18.034, Honors Differential Equations Prof. Jason Starr **Lecture 23** 4/2/04

0. Defined "integrable" and "of exponential type a". Spent the rest of the hour stating + proving properties of L. Used the notation $L[y(t)] = \underline{Y}(s)$.

- (1) Rigorously proved that if $y, y, \dots, y^{(n)}$ are of exponential type so, then $L[y^{(n)}] = s^n \overline{Y}(s) - (y^{(n-1)}(0) + \dots + s^{n-1}y(0)), s > s_0.$
- (2) Computed directly that L[1] = $\frac{1}{s}$, s > 0
- (3) Used (1) to prove that for a polynomial of ∂ 's n, $L[p] = \frac{1}{s^{n+1}} [p^{(n)}(0) + sp^{(n-1)}(0) + \dots + s^{n-1}p(0)], s > 0$ (by using that $L[p^{(n+1)}] = 0$). In particular, $L[t^n] = \frac{n!}{s^{n+1}}, s > 0$.
- (4) Used that $\sin(\omega t)$ and $\cos(\omega t)$ satisfy $y'' = \omega^2 y$, to deduce, $L[\sin(\omega t)] = \frac{\omega}{s^2 + \omega^2}$. Tested (1) by using that $\cos(\omega t) = -\omega \sin(\omega t) \cos(\omega t) = -\omega \sin(\omega t)$.
- (5) For a > 0, $L[y(at)] = \frac{1}{a} \Upsilon\left(\frac{s}{a}\right)$ by chze-of-variable.
- (6) Introduced notation for the unit step function $s(t) = \begin{cases} 1, t \ge 0 & \underline{Shift rule}: \quad L[s(t-t_0)y(t-t_0)] = e^{-st_0} Y(s) \\ 0, t < 0 & \text{for } t_0 > 0. \end{cases}$
- (7) $L[e^{at}y(t)] = \underline{Y}(s-a)$.
- (8) $L[R(t t_0)] = e^{-st_0}$ for $t_0 \ge 0$.
- (9) $L[t^n y(t)] = (-1)^n \frac{d^n}{ds^n} \Upsilon$ (*s*). Used this to double-check that $L[t^n] = \frac{n!}{s^{n-1}}$.

Used (8) + (1) to deduce $L\left[\frac{d}{ds}R(t-t_0)\right] = se^{-st_0}$ for $t_0 \ge 0$.

Discussed consistency of this with the derivation \sum_{α}^{∞}

$$\int_{-\infty} g(t) R'(t-t_0) dt = -\int_{-\infty} g'(t) R(t-t_0) dt = -g'(t_0)$$

for g a smooth, compactly supported function.