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18.02 Multivariable Calculus Fall 2007

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18.02 Lecture 16. – Thu, Oct 18, 2007

Handouts: PS6 solutions, PS7.

Double integrals.

Recall integral in 1-variable calculus: $\int_a^b f(x) dx$ = area below graph y = f(x) over [a, b].

Now: double integral $\iint_R f(x,y) dA$ = volume below graph z = f(x,y) over plane region R.

Cut R into small pieces $\Delta A \Rightarrow$ the volume is approximately $\sum f(x_i, y_i) \Delta A_i$. Limit as $\Delta A \to 0$ gives $\iint_R f(x, y) dA$. (picture shown)

How to compute the integral? By taking slices: S(x) = area of the slice by a plane parallel to yz-plane (picture shown): then

volume =
$$\int_{x_{min}}^{x_{max}} S(x) dx$$
, and for given $x, S(x) = \int f(x, y) dy$.

In the inner integral, x is a fixed parameter, y is the integration variable. We get an *iterated integral*.

Example 1: $z = 1 - x^2 - y^2$, region $0 \le x \le 1$, $0 \le y \le 1$ (picture shown):

$$\int_0^1 \int_0^1 (1 - x^2 - y^2) \, dy \, dx.$$

(note: dA = dy dx, limit of $\Delta A = \Delta y \Delta x$ for small rectangles).

How to evaluate:

1) inner integral (x is constant):
$$\int_{0}^{1} (1 - x^{2} - y^{2}) dy = \left[(1 - x^{2})y - \frac{1}{3}y^{3} \right]_{0}^{1} = (1 - x^{2}) - \frac{1}{3} = \frac{2}{3} - x^{2}.$$

2) outer integral:
$$\int_{0}^{1} (\frac{2}{3} - x^{2}) dx = \left[\frac{2}{3}x - \frac{1}{3}x^{3} \right]_{0}^{1} = \frac{2}{3} - \frac{1}{3} = \frac{1}{3}.$$

Example 2: same function over the quarter disc
$$R: x^2 + y^2 < 1$$
 in the first quadrant.

How to find the bounds of integration? Fix x constant: what is a slice parallel to y-axis? bounds for y = from y = 0 to $y = \sqrt{1 - x^2}$ in the inner integral. For the outer integral: first slice is x = 0, last slice is x = 1. So we get:

$$\int_0^1 \int_0^{\sqrt{1-x^2}} (1-x^2-y^2) \, dy \, dx$$

(note the inner bounds depend on the outer variable x; the outer bounds are constants!)

Inner:
$$[(1-x^2)y - y^3/3]_0^{\sqrt{1-x^2}} = \frac{2}{3}(1-x^2)^{3/2}.$$

Outer: $\int_0^1 \frac{2}{3}(1-x^2)^{3/2} dx = \dots = \frac{\pi}{8}.$

 $(\dots = \text{trig. substitution } x = \sin \theta, \, dx = \cos \theta \, d\theta, \, (1 - x^2)^{3/2} = \cos^3 \theta.$ Then use double angle formulas... complicated! I carried out part of the calculation to show how it would be done but then stopped before the end to save time; students may be confused about what happened exactly.)

Exchanging order of integration.

 $\int_0^1 \int_0^2 dx \, dy = \int_0^2 \int_0^1 dy \, dx$, since region is a rectangle (shown). In general, more complicated!

Example 3: $\int_0^1 \int_x^{\sqrt{x}} \frac{e^y}{y} dy dx$: inner integral has no formula. To exchange order:

1) draw the region (here: $x < y < \sqrt{x}$ for $0 \le x \le 1$ – picture drawn on blackboard).

2) figure out bounds in other direction: fixing a value of y, what are the bounds for x? here: left border is $x = y^2$, right is x = y; first slice is y = 0, last slice is y = 1, so we get

$$\int_0^1 \int_{y^2}^y \frac{e^y}{y} \, dx \, dy = \int_0^1 \frac{e^y}{y} (y - y^2) \, dy = \int_0^1 e^y - y e^y \, dy = [-y e^y + 2e^y]_0^1 = e - 2$$

(the last integration can be done either by parts, or by starting from the guess $-ye^y$ and adjusting;).

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Integration in polar coordinates. $(x = r \cos \theta, y = r \sin \theta)$: useful if either integrand or region have a simpler expression in polar coordinates.

Area element: $\Delta A \simeq (r\Delta\theta) \Delta r$ (picture drawn of a small element with sides Δr and $r\Delta\theta$). Taking $\Delta\theta, \Delta r \to 0$, we get $dA = r dr d\theta$.

Example (same as last time):
$$\iint_{x^2+y^2 \le 1, x \ge 0, y \ge 0} (1 - x^2 - y^2) \, dx \, dy = \int_0^{\pi/2} \int_0^1 (1 - r^2) \, r \, dr \, d\theta.$$

Inner: $\left[\frac{1}{2}r^2 - \frac{1}{4}r^4\right]_0^1 = \frac{1}{4}$. Outer: $\int_0^{\pi/2} \frac{1}{4} \, d\theta = \frac{\pi}{2} \frac{1}{4} = \frac{\pi}{8}$.

In general: when setting up $\iint f r \, dr \, d\theta$, find bounds as usual: given a fixed θ , find initial and final values of r (sweep region by rays).

Applications.

1) The area of the region R is $\iint_R 1 \, dA$. Also, the total mass of a planar object with density $\delta = \lim_{\Delta A=0} \Delta m / \Delta A$ (mass per unit area, $\delta = \delta(x, y)$ – if uniform material, constant) is given by:

$$M = \iint_R \delta \, dA.$$

2) recall the average value of f over R is $\overline{f} = \frac{1}{Area} \iint_R f \, dA$. The center of mass, or centroid, of a plate with density δ is given by weighted average

$$\bar{x} = \frac{1}{mass} \iint_R x \,\delta \, dA, \qquad \bar{y} = \frac{1}{mass} \iint_R y \,\delta \, dA$$

3) moment of inertia: physical equivalent of mass for rotational motion. (mass = how hard it is to impart translation motion; moment of inertia about some axis = same for rotation motion around that axis)

Idea: kinetic energy for a single mass m at distance r rotating at angular speed $\omega = d\theta/dt$ (so velocity $v = r\omega$) is $\frac{1}{2}mv^2 = \frac{1}{2}mr^2\omega^2$; $I_0 = mr^2$ is the moment of inertia.

For a solid with density δ , $I_0 = \iint_R r^2 \delta dA$ (moment of inertia / origin). (the rotational energy is $\frac{1}{2}I_0\omega^2$).

Moment of inertia about an axis: $I = \iint_R (\text{distance to axis})^2 \delta \, dA$. E.g. about *x*-axis, distance is |y|, so

$$I_x = \iint_R y^2 \delta \, dA$$

Examples: 1) disk of radius *a* around its center ($\delta = 1$):

$$I_0 = \int_0^{2\pi} \int_0^a r^2 r \, dr \, d\theta = 2\pi \left[\frac{r^4}{4}\right]_0^a = \frac{\pi a^4}{2}.$$

2) same disk, about a point on the circumference?

Setup: place origin at point so integrand is easier; diameter along x-axis; then polar equation of circle is $r = 2a \cos \theta$ (explained on a picture). Thus

$$I_0 = \int_{-\pi/2}^{\pi/2} \int_0^{2a\cos\theta} r^2 r \, dr \, d\theta = \dots = \frac{3}{2}\pi a^4.$$