Lecture 1. September 8, 2005

Homework. Problem Set 1 Part I: (a)–(e); Part II: Problems 1 and 2.

Practice Problems. Course Reader: 1B-1, 1B-2

Textbook: p. 68, Problems 1–7 and 15.

1. Velocity. Displacement is s(t). Increment from t_0 to $t_0 + \Delta t$ is,

$$\Delta s = s(t_0 + \Delta t) - s(t_0).$$

Average velocity from t_0 to $t_0 + \Delta t$ is,

$$v_{\rm ave} = \frac{\Delta s}{\Delta t} = \frac{s(t_0 + \Delta t) - s(t_0)}{\Delta t}.$$

Velocity, or *instantaneous velocity*, at t_0 is,

$$v(t_0) = \lim_{\Delta t \to 0} v_{\text{ave}} = \lim_{\Delta t \to 0} \frac{s(t_0 + \Delta t) - s(t_0)}{\Delta t}.$$

This is a *derivative*, v(t) equals s'(t) = ds/dt. The derivative of velocity is **acceleration**,

$$a(t_0) = v'(t_0) = \lim_{\Delta t \to 0} \frac{v(t_0 + \Delta t) - v(t_0)}{\Delta t}$$

Example. For $s(t) = -5t^2 + 20t$, first computed velocity at t = 1 is,

$$v(1) = \lim_{\Delta t \to 0} 10 - 5\Delta t = 10.$$

Then computed velocity at $t = t_0$ is,

$$v(t_0) = \lim_{\Delta t \to 0} -10t_0 + 10 - 5\Delta t = -10t_0 + 20.$$

Finally, computed acceleration at $t = t_0$ is,

$$a(t_0) = \lim_{\Delta t \to 0} -10 = -10.$$

2. Derivative. Let y = f(x) be a dependent variable depending on an independent variable x, varying freely. The increment of y from x_0 to $x_0 + \Delta x$ is,

$$\Delta y = f(x_0 + \Delta x) - f(x_0).$$

The difference quotient or average rate-of-change of y from x_0 to $x_0 + \Delta x$ is,

$$\frac{\Delta y}{\Delta x} = \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}.$$

The *derivative* of y (or f(x)) with respect to x at x_0 is,

$$\lim_{\Delta x \to 0} \frac{\Delta y}{\Delta x} = \lim_{\Delta x \to 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}.$$

3. Examples in science and math.

- (i) Economics. *Marginal cost* is the derivative of cost with respect to some other variable, for instance, the quantity purchased.
- (ii) Thermodynamics. The ideal gas law relating pressure p, volume V, and temperature T of a gas is,

$$pV = nRT.$$

Under isothermal conditions, T is a constant T_0 so that,

$$p(V) = \frac{nRT_0}{V}.$$

Under adiabatic conditions (i.e., no transfer of heat), pV^{γ} is a constant K. Using this to eliminate p gives,

$$T(V) = \frac{K}{nR} \frac{1}{V^{\gamma-1}}.$$

As this illustrates, the independent variable, dependent variable and constants in an equation very much depend on the problem to be solved.

(iii) Biology. Exponential population growth models the population N(t) after t years as,

$$N(t) = N_0 e^{rt},$$

where e^x is the exponential function, N_0 is initial population, and r is a growth factor. Later we will see, N'(t) = rN(t), i.e., the population grows at a rate proportional to the size of the population.

(iv) Geometry. The volume of a right circular cone is,

$$V = \frac{1}{3}A \times h.$$

where A is the base area of the cone and h is the height of the cone. The radius r of the base is proportional to the height,

$$r(h) = ch,$$

for some constant c. Since $A = \pi r^2$, this gives,

$$V(h) = \frac{\pi}{3}c^2h^3.$$

The derivative is,

$$\frac{dV}{dh} = \pi c^2 h^2 = \pi r^2 = \textbf{A}.$$

This is very reasonable. In some sense, this explains the classical formula for the volume of a cone.