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6.642 Continuum Electromechanics  
Fall 2008

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## Problem Set 2 - Solutions

## Problem 1

## Prob. 2.16.5

Gauss' law and  $\mathbf{E} = -\nabla\Phi$  requires that if there is no free charge

$$\epsilon\nabla^2\Phi + \nabla\epsilon \cdot \nabla\Phi = 0 \quad (1)$$

For the given exponential dependence of the permittivity, the  $x$  dependence of the coefficients in this expression factors out and it again reduces to a constant coefficient expression

$$\frac{\partial^2\Phi}{\partial x^2} + \frac{\partial^2\Phi}{\partial y^2} + \frac{\partial^2\Phi}{\partial z^2} + 2\eta\frac{\partial\Phi}{\partial x} = 0 \quad (2)$$

In terms of the complex amplitude forms from Table 2.16.1, Eq. 2 requires that

$$\frac{d^2\tilde{\Phi}}{dx^2} + 2\eta\frac{d\tilde{\Phi}}{dx} - k^2\tilde{\Phi} = 0 \quad (3)$$

Thus, solutions have the form  $\exp(px)$  where  $p = -\eta \pm \lambda$ ,  $\lambda = \sqrt{k^2 - \eta^2}$ .

The linear combination of these that satisfies the conditions that  $\tilde{\Phi}$  be  $\tilde{\Phi}^\alpha$  and  $\tilde{\Phi}^\beta$  on the upper and lower surfaces respectively is as given in the problem. The displacement vector is then evaluated as

$$\tilde{D} = -\epsilon_\beta \left\{ \tilde{\Phi}^\alpha e^{\eta(x+\Delta)} \frac{-\eta \sinh \lambda x + \lambda \cosh \lambda x}{\sinh \lambda \Delta} - \tilde{\Phi}^\beta e^{\eta x} \frac{-\eta \sinh \lambda(x-\Delta) + \lambda \cosh \lambda(x-\Delta)}{\sinh \lambda \Delta} \right\} \quad (4)$$

Evaluation of this expression at the respective surfaces then gives the transfer relations summarized in the problem.

Courtesy of James R. Melcher. Used with permission. Solution to problem 2.16.5 in Melcher, James. Solutions Manual for *Continuum Electromechanics*. 1982, p. 2.28.

## Problem 2

## Prob. 4.3.3

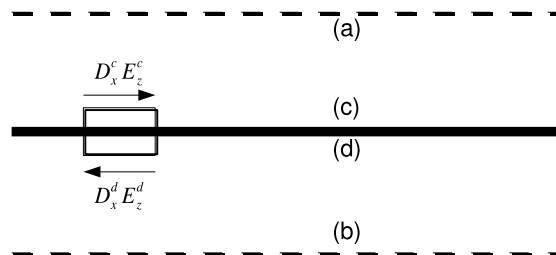


Figure 1: Force per unit area on middle charged surface (c/d) is found using the Maxwell stress tensor (Image by MIT OpenCourseWare.)

Courtesy of James R. Melcher. Used with permission. Solution to problem 4.3.3 in Melcher, James. Solutions Manual for *Continuum Electromechanics*. 1982, pp. 4.3-4.4.

With positions as designated in the sketch, the total force per unit area is

$$\langle f_z \rangle_z = \langle D_x^c E_z^c - D_x^d E_z^d \rangle_z = \frac{1}{2} \Re(\tilde{D}_x^c \tilde{E}_z^{c*} - \tilde{D}_x^d \tilde{E}_z^{d*}) \quad (5)$$

With the understanding that the surface charge on the sheet is a given quantity, boundary conditions reflecting the continuity of tangential electric field at the three surfaces and that Gauss' law be satisfied through the sheet are

$$\tilde{\Phi}^a \text{ given; } \tilde{\Phi}^b \text{ given; } \tilde{\Phi}^c = \tilde{\Phi}^d; \quad \tilde{D}_x^c - \tilde{D}_x^d = \tilde{\sigma}_f \text{ given} \quad (6)$$

Bulk relations are given by Table 2.16.1. In the upper region

$$\begin{bmatrix} \tilde{D}_x^a \\ \tilde{D}_x^c \end{bmatrix} = \epsilon_0 k \begin{bmatrix} -\coth kd & \frac{1}{\sinh kd} \\ -\frac{1}{\sinh kd} & \coth kd \end{bmatrix} \begin{bmatrix} \tilde{\Phi}^a \\ \tilde{\Phi}^c \end{bmatrix} \quad (7)$$

and in the lower

$$\begin{bmatrix} \tilde{D}_x^d \\ \tilde{D}_x^b \end{bmatrix} = \epsilon_0 k \begin{bmatrix} -\coth kd & \frac{1}{\sinh kd} \\ -\frac{1}{\sinh kd} & \coth kd \end{bmatrix} \begin{bmatrix} \tilde{\Phi}^d \\ \tilde{\Phi}^b \end{bmatrix} \quad (8)$$

In view of Eq. 6, Eq. 5 becomes

$$\langle f_z \rangle_z = \frac{1}{2} \Re[-jk\tilde{\sigma}_f \tilde{\Phi}^{c*}] \quad (9)$$

so what is now required is the amplitude  $\tilde{\Phi}^c$ . The surface charge, given by Eq. 6, as the difference  $\tilde{D}_x^c - \tilde{D}_x^d$ , follows in terms of the potentials from taking the difference of Eqs. 7 (second row) and 8 (first row). The resulting expression is solved for

$$\tilde{\Phi}^c = \frac{\tilde{\sigma}_f}{2\epsilon_0 k \coth kd} + \frac{\tilde{\Phi}^a + \tilde{\Phi}^b}{2 \cosh kd} \quad (10)$$

Substituted into Eq. 9 (where the self terms in  $\tilde{\sigma}_f \tilde{\sigma}_f^*$  are imaginary and can therefore be dropped) the force is expressed in terms of the given excitations

$$\langle f_z \rangle_z = \frac{1}{2} k \Re \left[ -j \tilde{\sigma}_f \frac{\tilde{\Phi}^{a*} + \tilde{\Phi}^{b*}}{2 \cosh kd} \right] \quad (11)$$

**b)**

Translation of the given excitations into complex amplitudes gives

$$\tilde{\sigma}_f = -\sigma_0 e^{j\omega t} e^{jk\delta}, \quad \tilde{\Phi}^a = V_0 e^{j\omega t}, \quad \tilde{\Phi}^b = \pm V_0 e^{j\omega t} \quad (12)$$

Thus, with the even excitation, where  $\Phi^a = \Phi^b$

$$\langle f_z \rangle_z = -\frac{kV_0\sigma_0}{2 \cosh kd} \sin k\delta \quad (13)$$

and with the odd excitation,  $\langle f_z \rangle_z = 0$ .

**c)**

This is a specific case from part (b) with  $\omega = 0$  and  $\delta = \lambda/4$ . Thus,

$$\langle f_z \rangle_z = -\frac{kV_0\sigma_0}{2 \cosh kd} \quad (14)$$

The sign is consistent with the sketch of charge distribution on the sheet and electric field due to the potentials on the walls sketched.

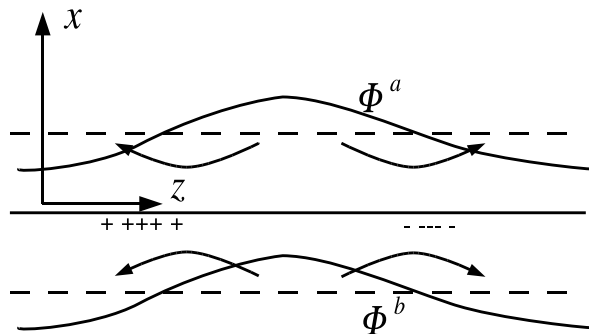


Figure 2: Potentials  $\Phi_a = \Phi_b = -V_0 \cos kz$  shown with surface charge  $\sigma_f = \sigma_0 \sin kz$  (Image by MIT OpenCourseWare.)

### Problem 3 (Zahn, Problem 23, Chapter 1)

a)

Cartesian	Cylindrical	Spherical
$h_x = 1$	$h_r = 1$	$h_r = 1$
$h_y = 1$	$h_\phi = r$	$h_\theta = r$
$h_z = 1$	$h_z = 1$	$h_\phi = r \sin \theta$

b)

$$\begin{aligned}
 df &= \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial v} dv + \frac{\partial f}{\partial w} dw \\
 &= \nabla f \cdot \bar{d}\ell \\
 &= \nabla f \cdot [h_u d\bar{i}_u + h_v d\bar{i}_v + h_w d\bar{i}_w] \\
 (\nabla f)_u &= \frac{1}{h_u} \frac{\partial f}{\partial u}; \quad (\nabla f)_v = \frac{1}{h_v} \frac{\partial f}{\partial v}; \quad (\nabla f)_w = \frac{1}{h_w} \frac{\partial f}{\partial w} \\
 \nabla f &= \frac{1}{h_u} \frac{\partial f}{\partial u} \bar{i}_u + \frac{1}{h_v} \frac{\partial f}{\partial v} \bar{i}_v + \frac{1}{h_w} \frac{\partial f}{\partial w} \bar{i}_w
 \end{aligned}$$

c)

$$\begin{aligned}
 dS_u &= h_v h_w dv dw; \quad dS_v = h_u h_w du dw; \quad dS_w = h_u h_v du dv \\
 dV &= h_u h_v h_w du dv dw
 \end{aligned}$$

d)

Divergence

$$\begin{aligned}
 \Phi &= \oint_S \bar{A} \cdot \bar{dS} = \int_{1,u} A_u h_v h_w dv dw - \int_{1',u-\Delta u} A_u h_v h_w dv dw \\
 &+ \int_{2,v+\Delta v} A_v h_u h_w du dw - \int_{2',v} A_v h_u h_w du dw
 \end{aligned}$$

$$\begin{aligned}
 & + \int_{3,w+\Delta w} A_w h_u h_v dudv - \int_{3',w} A_w h_u h_v dudv \\
 = & \left\{ \frac{A_u h_v h_w|_u - A_u h_v h_w|_{u-\Delta u}}{\Delta u} + \frac{A_v h_u h_w|_{v+\Delta v} - A_v h_u h_w|_v}{\Delta v} + \frac{A_w h_u h_v|_{w+\Delta w} - A_w h_u h_v|_w}{\Delta w} \right\} \Delta u \Delta v \Delta w \\
 \nabla \cdot \bar{A} = & \lim_{\Delta u \rightarrow 0, \Delta v \rightarrow 0, \Delta w \rightarrow 0} \frac{\oint_S \bar{A} \cdot \bar{dS}}{\Delta V} = \frac{\oint_S \bar{A} \cdot \bar{dS}}{h_u h_v h_w \Delta u \Delta v \Delta w} \\
 = & \frac{1}{h_u h_v h_w} \left[ \frac{\partial(h_v h_w A_u)}{\partial u} + \frac{\partial(h_u h_w A_v)}{\partial v} + \frac{\partial(h_u h_v A_w)}{\partial w} \right]
 \end{aligned}$$

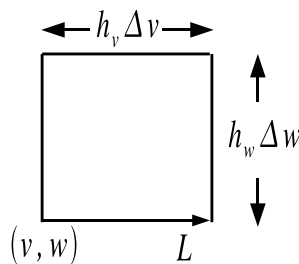


Figure 3: Contour for determining  $(\nabla \times \bar{A})_u$  (Image by MIT OpenCourseWare.)

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$$\begin{aligned}
 (\nabla \times \bar{A})_u = & \lim_{\Delta v \rightarrow 0, \Delta w \rightarrow 0} \frac{\oint_L \bar{A} \cdot \bar{d\ell}}{h_v h_w \Delta v \Delta w} \\
 \oint_L \bar{A} \cdot \bar{d\ell} = & [A_v h_v \Delta v|_w - A_v h_v \Delta v|_{w+\Delta w}] + [A_w h_w \Delta w|_{v+\Delta v} - A_w h_w \Delta w|_v] \\
 (\nabla \times \bar{A})_u = & \lim_{\Delta v \rightarrow 0, \Delta w \rightarrow 0} \frac{1}{h_v h_w} \left\{ \frac{A_v h_v|_w - A_v h_v|_{w+\Delta w}}{\Delta w} + \frac{A_w h_w|_{v+\Delta v} - A_w h_w|_v}{\Delta v} \right\} \\
 = & \frac{1}{h_v h_w} \left[ \frac{\partial(h_w A_w)}{\partial v} - \frac{\partial(h_v A_v)}{\partial w} \right]
 \end{aligned}$$

Similarly

$$\begin{aligned}
 (\nabla \times \bar{A})_v = & \frac{1}{h_u h_w} \left[ \frac{\partial(h_u A_u)}{\partial w} - \frac{\partial(h_w A_w)}{\partial u} \right] \\
 (\nabla \times \bar{A})_w = & \frac{1}{h_u h_v} \left[ \frac{\partial(h_v A_v)}{\partial u} - \frac{\partial(h_u A_u)}{\partial v} \right]
 \end{aligned}$$

e)

$$\nabla^2 f = \nabla \cdot (\nabla f) = \frac{1}{h_u h_v h_w} \left[ \frac{\partial}{\partial u} \left( \frac{h_v h_w}{h_u} \frac{\partial f}{\partial u} \right) + \frac{\partial}{\partial v} \left( \frac{h_u h_w}{h_v} \frac{\partial f}{\partial v} \right) + \frac{\partial}{\partial w} \left( \frac{h_u h_v}{h_w} \frac{\partial f}{\partial w} \right) \right]$$