

Free-Surface Waves

2.016 Fall 2005

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Ocean Waves

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Wave Breaking

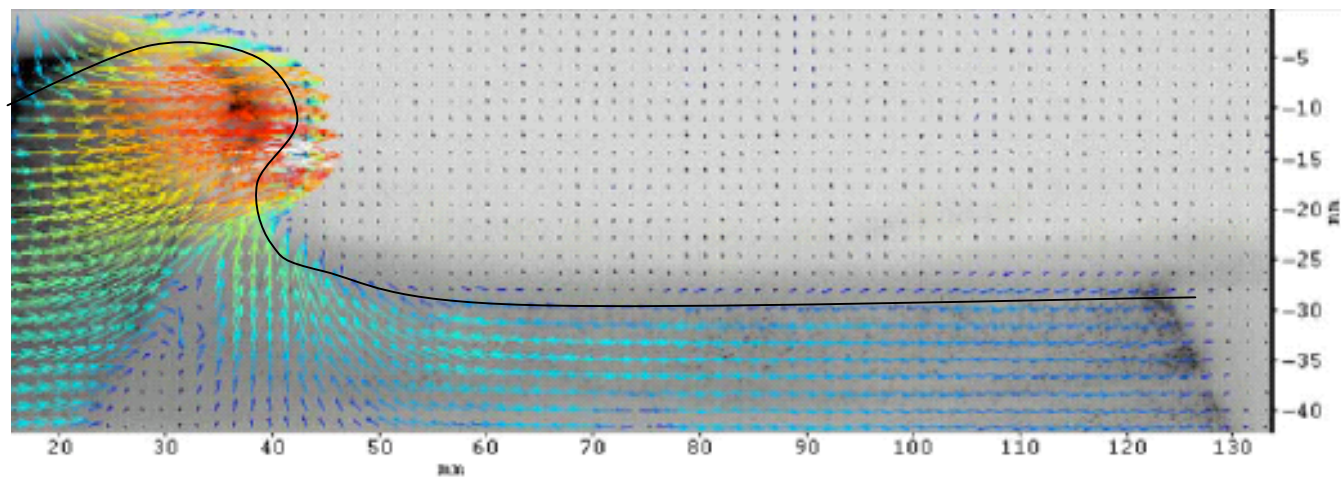
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Breaking wave in a Laboratory



PIV under the interface

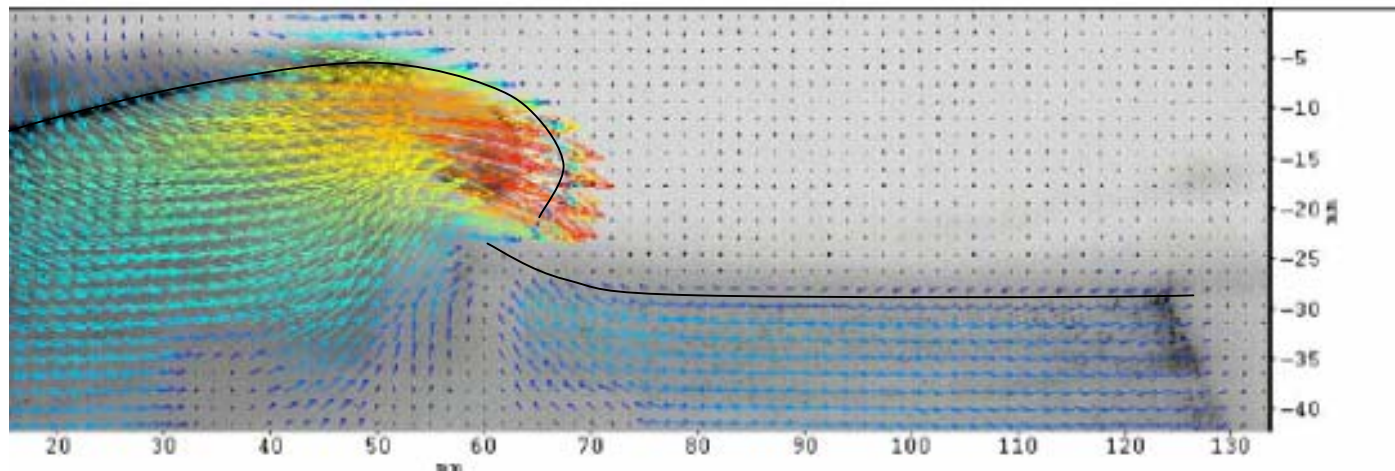
Plunging Breaker



$$\begin{aligned} We &= 4568, Re = 6.94 \times 10^5 \\ f &= 2.0 \text{ Hz}, \lambda = 0.366 \text{ m}, \sigma = 42 \text{ dynes/cm} \end{aligned}$$

PIV under the interface

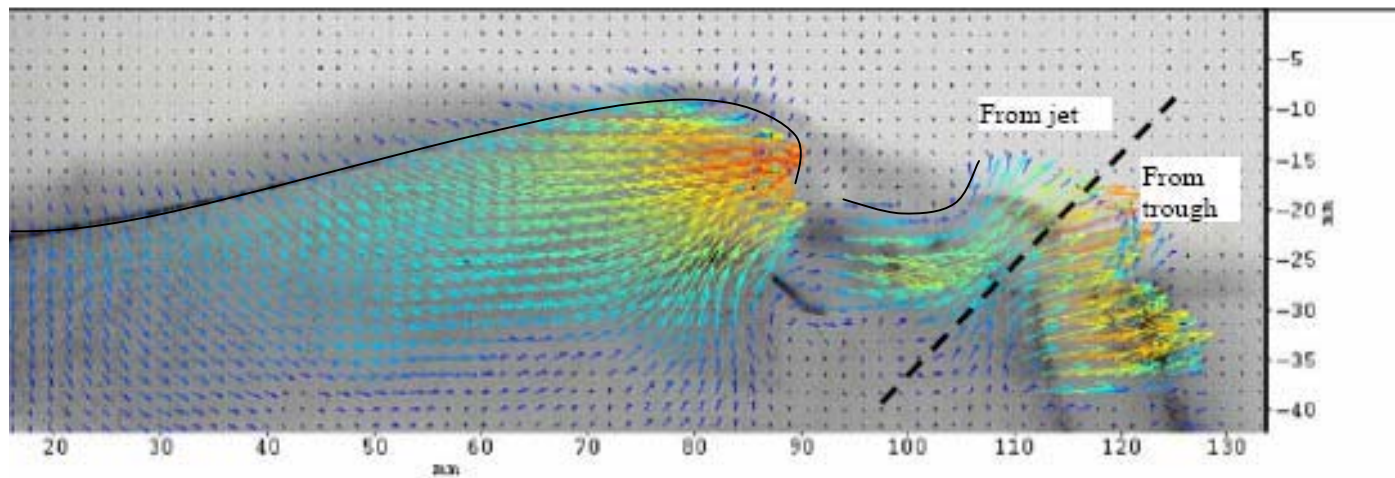
Plunging Breaker



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PIV under the interface

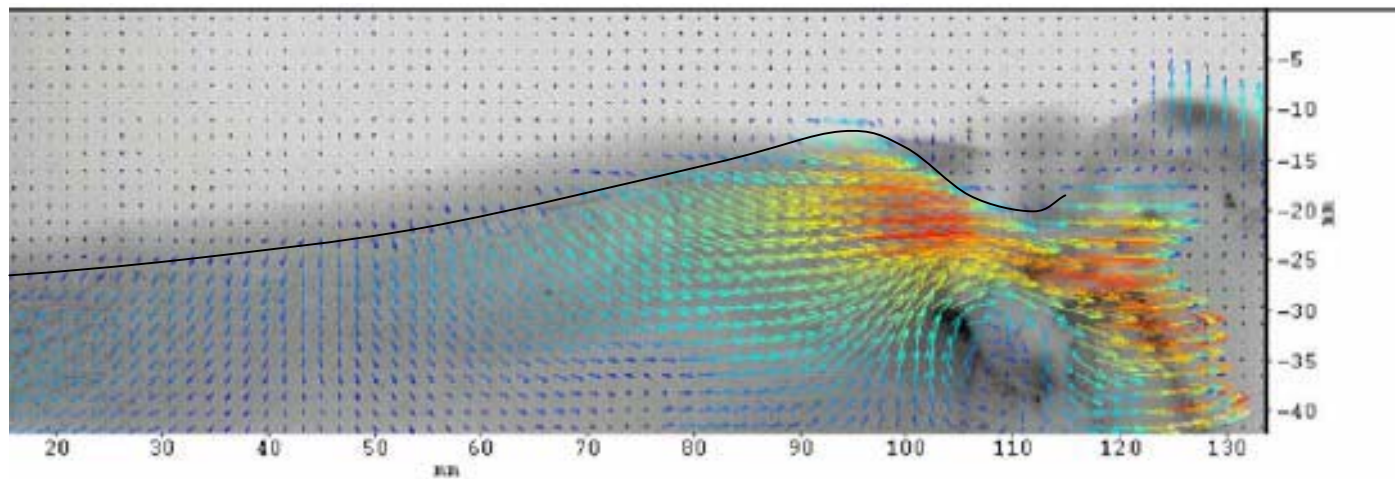
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PIV under the interface

Plunging Breaker

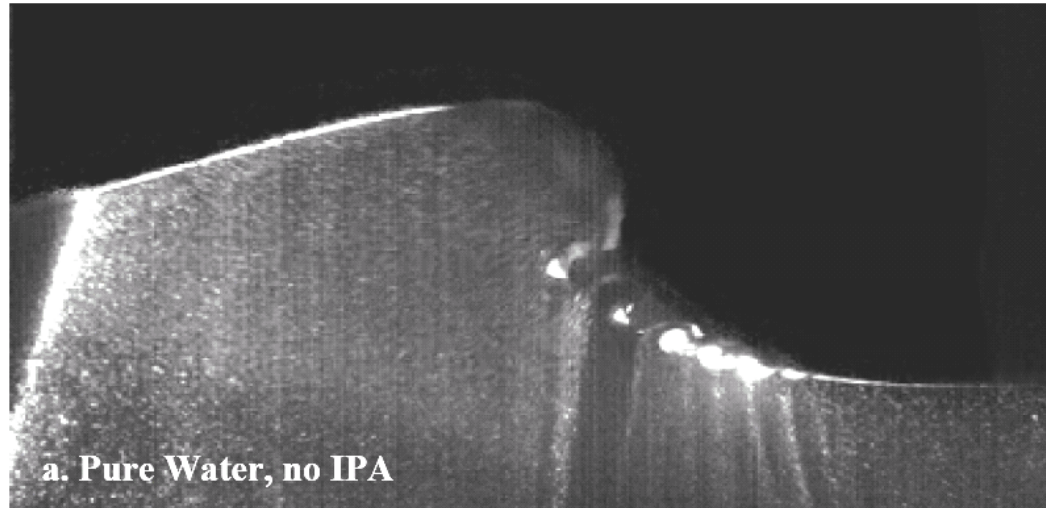


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Effect of Surface Tension on wave profile

Pure Distilled Water

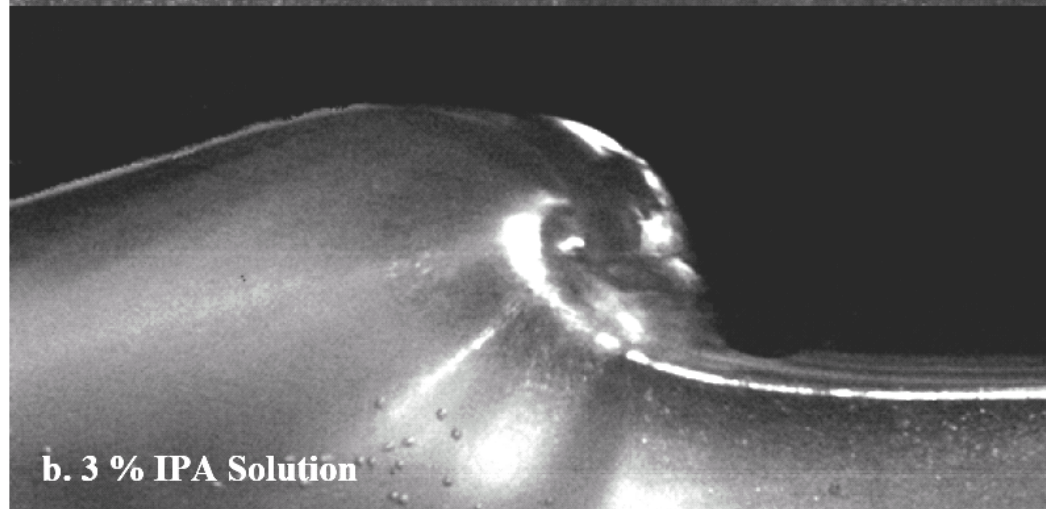
Clean Tank Conditions



Higher surface tension

**Distilled Water
+ 3% IPA**

Clean Tank Conditions



Lower surface tension

Causes of Ocean Waves

- Wind blowing across the ocean surface
 - Frequency $f = 10^{-2}$ to 10^2 Hz
 - Period $T = 1/f = 0.01$ to 100 seconds
- Pull of the sun and moon
 - Frequency is on the order 10^{-4} to 10^{-6} Hz
 - Period $T = 12, 24$ hours (tides)
- Earthquakes – e.g. Tsunamis
 - Frequency less than 10^{-2} Hz
 - Long wave period

OCEAN WAVES SPECTRUM

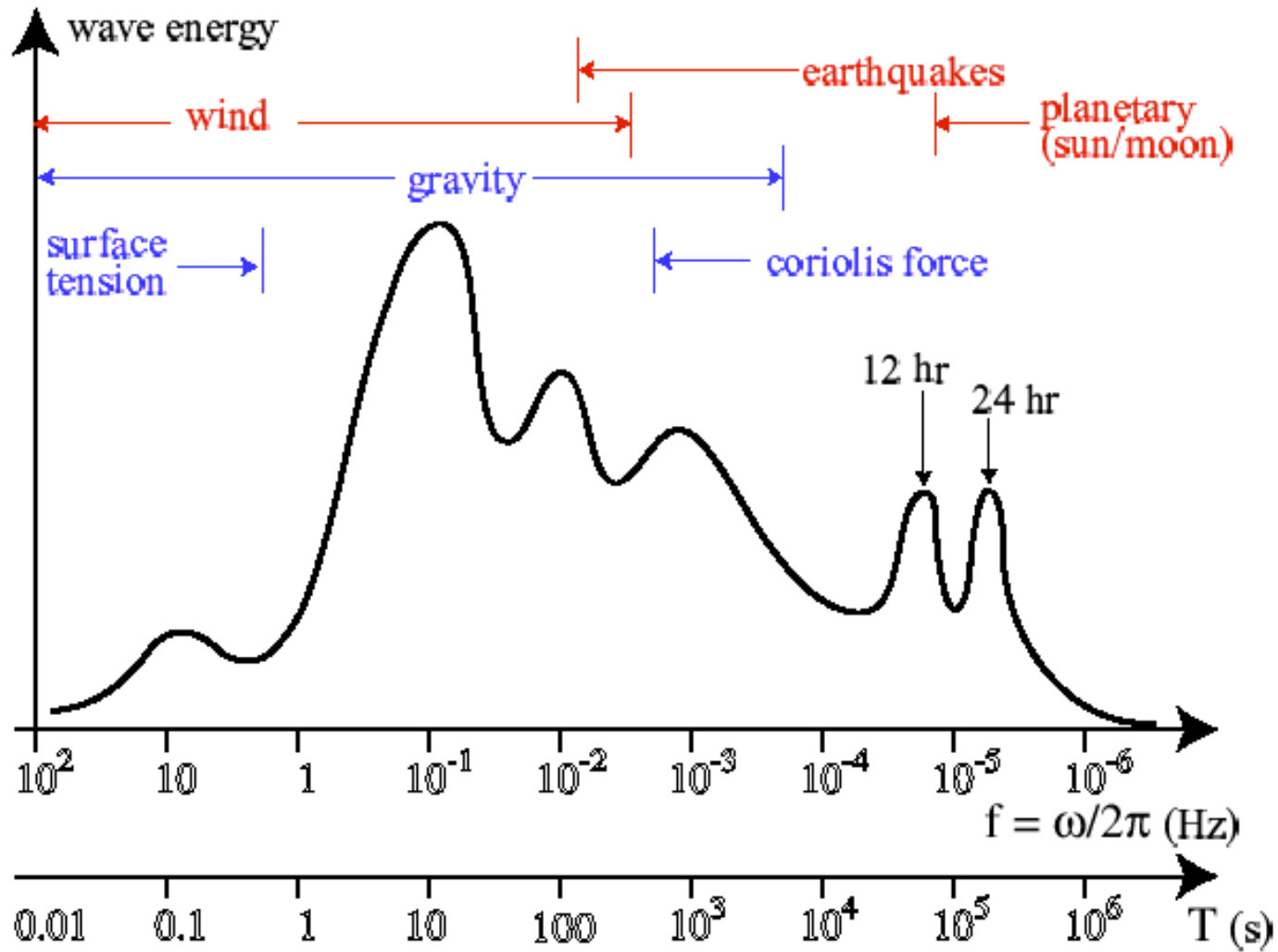
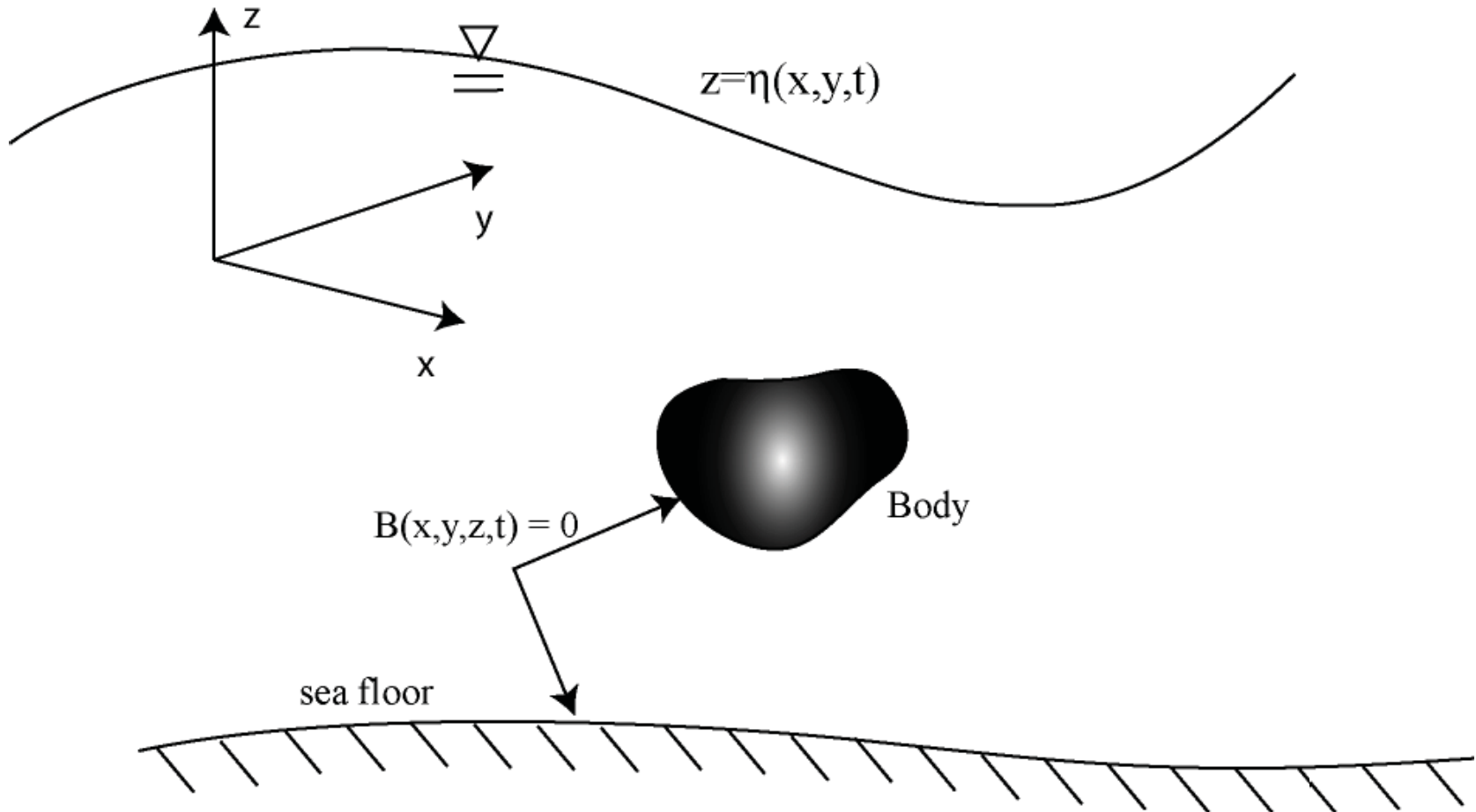


FIGURE 1. Wave energy spectra. Red text indicates wave generation mechanisms and blue text indicates damping/restoring forces.

World Meteorological Org. Sea State Codes

Sea State Code	Significant Wave Height		Description
	Range	Mean	
0	0 (meters)	0 (meters)	Calm (glassy)
1	0-0.1	0.05	Calm (rippled)
2	0.1-0.5	0.3	Smooth (mini-waves)
3	0.5-1.25	0.875	Slight
4	1.25-2.5	1.875	Moderate
5	2.5-4.0	3.25	Rough
6	4.0-6.0	5.0	Very Rough
7	6.0-9.0	7.5	High
8	9.0-14.0	11.5	Very High
9	> 14.0	> 14.0	Huge

General Wave Problem



Unknowns

- Velocity Field

$$\vec{V}(x, y, z, t) = \nabla\phi(x, y, z, t)$$

- Free Surface Elevation

$$z(x, y, t) = \eta(x, y, t)$$

- Pressure Field

$$p(x, y, z, t) = p_{dynamic} + p_{hydrostatic}$$

Governing Equations & Conditions

- Continuity (Conservation of Mass):

$$\nabla^2 \phi = 0 \text{ for } z < \eta$$

- Bernoulli's Equation (given ϕ):

$$\frac{\partial \phi}{\partial t} + \frac{1}{2} |\nabla \phi|^2 + \frac{p - p_a}{\rho} + gz = 0 \text{ for } z < \eta$$

- No disturbance exists far away:

$$\frac{\partial \phi}{\partial t}, \nabla \phi \rightarrow 0 \text{ and } p = p_a - \rho gz$$

Boundary Conditions

- In order to solve the boundary value problem for free surface waves we need to understand the boundary conditions on the free surface, any bodies under the waves, and on the sea floor:
 - Pressure is constant across the interface
 - Once a particle on the free surface, it remains there always.
 - No flow through an impervious boundary or body.

Pressure Across the FS Interface

$$p = p_{atm} \text{ on } z = \eta$$

Bernoulli's Eqn. \longrightarrow at the free surface $p + \rho \left\{ \frac{\partial \phi}{\partial t} + \frac{1}{2} V^2 + gz \right\} = c(t)$

$$p = -\rho \left\{ \frac{\partial \phi}{\partial t} + \frac{1}{2} V^2 + gz \right\} + c(t) = p_{atm}$$

Since $c(t)$ is arbitrary we can choose a suitable constant that fits our needs:

$$c(t) = p_{atm}$$

Thus our pressure boundary condition on $z = \eta$ becomes:

$$\rho \left\{ \frac{\partial \phi}{\partial t} + \frac{1}{2} V^2 + g\eta \right\} = 0$$

Once a Particle on the FS...

The normal velocity of a particle on the FS follows the normal velocity of the surface itself:

$$z_p = \eta(x_p, t) \quad \text{z-position of the particle}$$

Look at small motion δz_p :

$$z_p + \delta z_p = \eta(x_p + \delta x_p, t + \delta t) = \eta(x_p, t) + \frac{\partial \eta}{\partial x} \delta x_p + \frac{\partial \eta}{\partial t} \delta t$$

On the surface, where $z_p = \eta$, this reduces to:

$$\delta z_p = \frac{\partial \eta}{\partial x} \frac{\delta x_p}{\delta t} \delta t + \frac{\partial \eta}{\partial t} \delta t \quad \frac{\delta x_p}{\delta t} = u \quad \frac{\delta z_p}{\delta t} = w$$

$$\therefore w = u \frac{\partial \eta}{\partial x} + \frac{\partial \eta}{\partial t} \quad \text{on } z = \eta$$

No flow through an impervious boundary

Velocity of the fluid normal to the body must be equal to the body velocity in that direction:

On the Body: $B(x, y, z, t) = 0$

$$\vec{V} \cdot \hat{n} = \nabla \phi \cdot \hat{n} = \frac{\partial \phi}{\partial n} = \vec{U}(\vec{x}, t) \cdot \hat{n}(\vec{x}, t) = U_n \quad \text{on } B = 0$$

Alternately a particle P on B remains on B always; i.e. B is a material surface.

For example: if P is on B at some time $t = t_o$ such that $B(x, t_o) = 0$ and we were to follow P then B will be always zero:

If $B(\vec{x}, t_o) = 0$, then $B(\vec{x}, t) = 0$ for all t ,

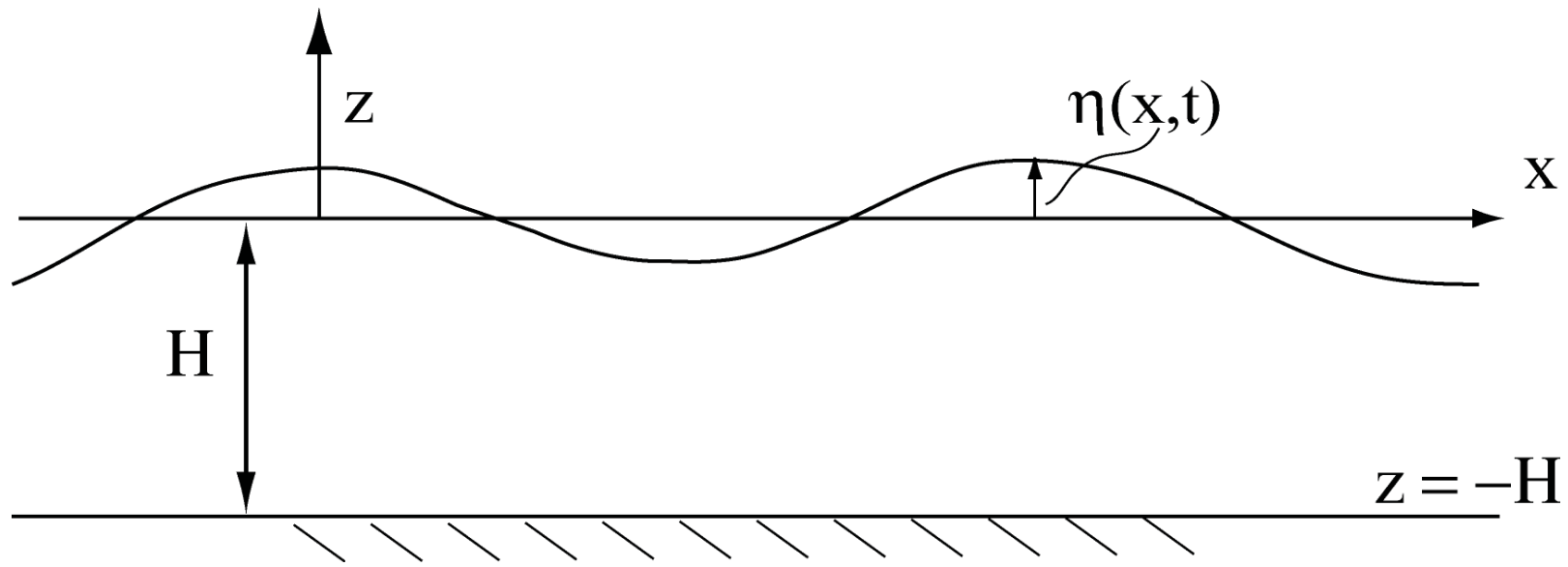
$$\therefore \frac{DB}{Dt} = \frac{\partial B}{\partial t} + (\nabla \phi \cdot \nabla) B = 0 \quad \text{on } B = 0$$

Take for example a flat bottom at $z = -H$ then $\partial \phi / \partial z = 0$

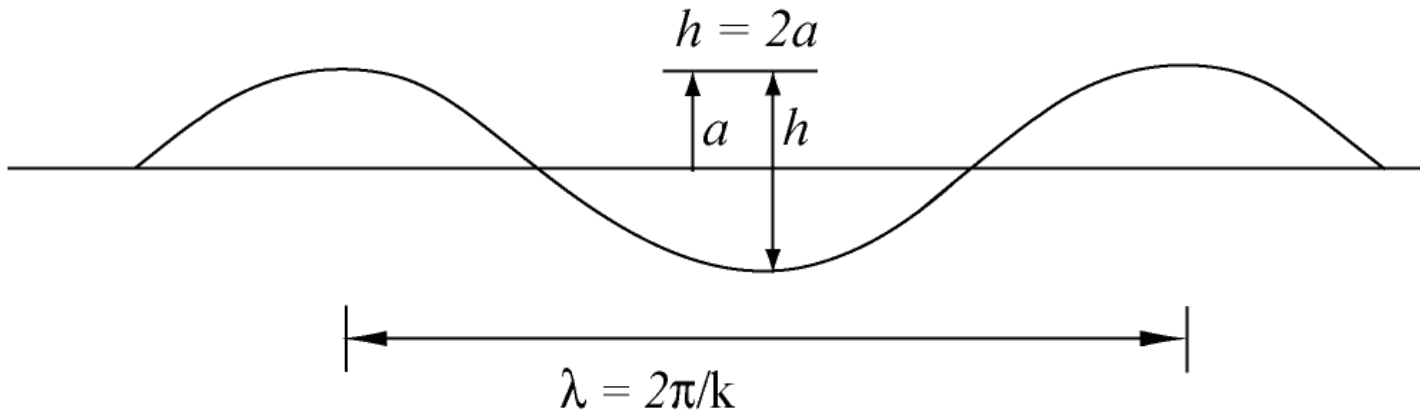
Linear Plane Progressive Waves

Linear free-surface gravity waves can be characterized by their amplitude, a , wavelength, $\lambda = 2\pi/k$, and frequency, ω .

$$\eta(x, t) = a \cos(kx - \omega t)$$



Linear Waves



- a is wave amplitude, $h = 2a$
- λ is wavelength, $\lambda = 2\pi/k$ where k is wave number
- Waves will start to be non-linear (and then break) when $h/\lambda > 1/7$

Linearization of Equations & Boundary Conditions

Non-dimensional variables :

$$\eta = a \eta^* \quad u = a\omega u^* \quad \omega t = t^*$$

$$\phi = a\omega\lambda \phi^* \quad w = a\omega w^* \quad x = \lambda x^*$$

$$dt = 1/\omega dt^* \quad d\phi = a\omega\lambda d\phi^* \quad dx = \lambda dx^*$$

FS Boundary Conditions

1. Dynamic FS BC:
(Pressure at the FS) $\rho \left\{ \frac{\partial \phi}{\partial t} + \frac{1}{2} V^2 + g\eta \right\} = 0$

Compare $\frac{\partial \phi}{\partial t}$ and $V^2 \sim \left(\frac{\partial \phi}{\partial x} \right)^2$

$$\frac{\left(\frac{\partial \phi}{\partial x} \right)^2}{\frac{\partial \phi}{\partial t}} = \frac{a^2 \omega^2 \left(\frac{\partial \phi^*}{\partial x^*} \right)}{a \omega^2 \lambda \frac{\partial \phi^*}{\partial t^*}} = \frac{a}{\lambda} \frac{\left(\frac{\partial \phi^*}{\partial x^*} \right)}{\frac{\partial \phi^*}{\partial t^*}}$$

If $h/\lambda \ll 1/7$ then $a/\lambda \ll 1/14$ since $h = 2a$.

$$\left(\frac{\partial \phi}{\partial x} \right)^2 \ll \frac{\partial \phi}{\partial t}$$

$\therefore \rho \left\{ \frac{\partial \phi}{\partial t} + \frac{1}{2} V^2 + g\eta \right\} = 0$ becomes $\frac{\partial \phi}{\partial t} + g\eta = 0$ on $z = \eta$

FS Boundary Conditions

2. Kinematic FS BC:
(Motion at the Surface) $w = u \frac{\partial \eta}{\partial x} + \frac{\partial \eta}{\partial t}$

Non-dimensionalize:

$$\cancel{a\omega} w^* = \cancel{a\omega} u^* \frac{a}{\lambda} \frac{\partial \eta^*}{\partial x^*} + \cancel{a\omega} \frac{\partial \eta^*}{\partial t^*}$$

If $h/\lambda \ll 1/7 \Rightarrow u \frac{\partial \eta}{\partial x} \ll \frac{\partial \eta}{\partial t}$ and $u \frac{\partial \eta}{\partial x} \ll w$

Therefore:

$w = u \frac{\partial \eta}{\partial x} + \frac{\partial \eta}{\partial t}$ becomes $\frac{\partial \phi}{\partial z} = \frac{\partial \eta}{\partial t}$ on $z = \eta$

FSBC about $z=0$

Since wave elevation, η , is proportional to wave amplitude, a , and a is small compared to the wavelength, λ , we can simplify our boundary conditions one step further to show that they can be taken at $z = 0$ versus $z = \eta$.

First take the Taylor's series expansion of $\phi(x, z=\eta, t)$ about $z=0$:

$$\phi(x, z = \eta, t) = \phi(x, 0, t) + \frac{\partial \phi}{\partial z} \eta + \dots$$

It can be shown that the second order term and all subsequent HOTs are very small and can be neglected. Thus we can substitute $\phi(x, z=0, t)$ for $\phi(x, z=\eta, t)$ everywhere:

$$\frac{\partial \phi}{\partial t} + g\eta = 0 \quad \Rightarrow \quad \boxed{\eta = -\frac{1}{g} \frac{\partial \phi}{\partial t}} \quad \Rightarrow \quad \frac{\partial \eta}{\partial t} = -\frac{1}{g} \frac{\partial^2 \phi}{\partial t^2}$$

$$\frac{\partial \phi}{\partial z} = \frac{\partial \eta}{\partial t} \quad \Rightarrow \quad \boxed{\frac{\partial \phi}{\partial z} + \frac{1}{g} \frac{\partial^2 \phi}{\partial t^2} = 0 \text{ on } z = 0}$$

Linear Wave Boundary Value Problem

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \text{ for } z < 0$$

1. Sea Floor Boundary Condition (flat bottom)

$$\frac{\partial \phi}{\partial z} = 0 \text{ on } z = -H$$

2. Dynamic FSBC (Pressure at the FS)

$$\eta = -\frac{1}{g} \frac{\partial \phi}{\partial t} \text{ on } z = 0$$

3. Kinematic FSBC (Motion at the Surface)

$$\frac{\partial^2 \phi}{\partial t^2} + g \frac{\partial \phi}{\partial z} = 0 \text{ on } z = 0$$

Solution to Laplace's Equation

By Separation of Variables we can get a solution for linear FS waves:

$$\eta(x, t) = a \cos(kx - \omega t + \psi)$$

$$\phi(x, z, t) = \frac{a\omega}{k} f(z) \sin(kx - \omega t + \psi)$$

$$u(x, z, t) = a\omega f(z) \cos(kx - \omega t + \psi)$$

$$w(x, z, t) = a\omega f_1(z) \sin(kx - \omega t + \psi)$$

$$\omega^2 = gk \tanh(kH) \Rightarrow \text{dispersion relation}$$

Where:

$$f(z) = \frac{\cosh[k(z + H)]}{\sinh(kH)} \quad f_1(z) = \frac{\sinh[k(z + H)]}{\sinh(kH)}$$

Dispersion Relationship

The dispersion relationship uniquely relates the wave frequency and wave number given the depth of the water.

$$\omega^2 = gk \tanh(kH)$$

The solution ϕ must satisfy all boundary conditions.

Plugging ϕ into the KBC yields the dispersion relationship

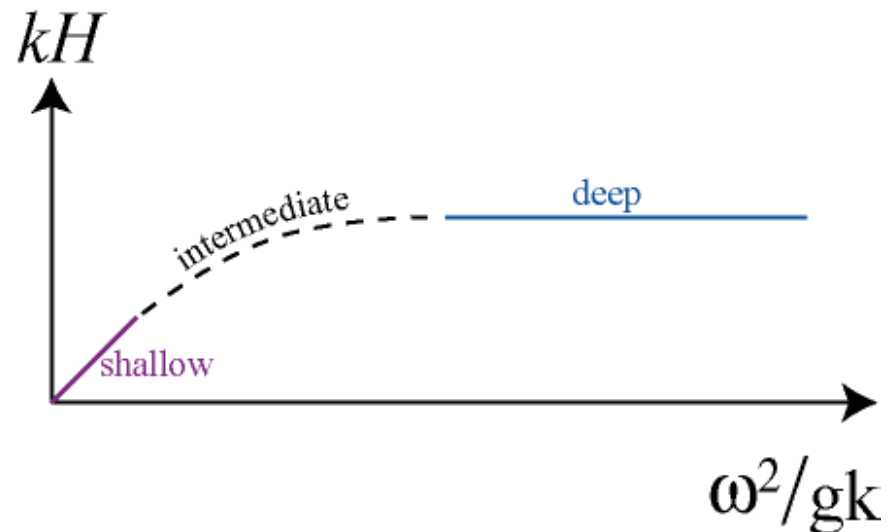
- Approximations

– As $kH \rightarrow 0$ $\tanh(kH) \rightarrow kH$

$\therefore \omega^2 \cong gk^2 H$ (shallow)

– As $kH \rightarrow \infty$ $\tanh(kH) \rightarrow 1$

$\therefore \omega^2 \cong gk$ (deep)



Pressure Under Waves

Unsteady Bernoulli's Equation:

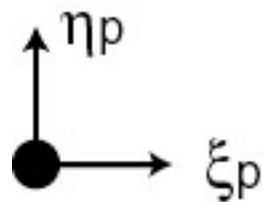
$$p = - \underbrace{\rho \frac{\partial \phi}{\partial t}}_{\text{unsteady fluctuation}} - \underbrace{\frac{1}{2} \rho V^2}_{\text{2nd Order term}} - \underbrace{\rho g z}_{\text{hydrostatic pressure}}$$

Dynamic Pressure

Since we are dealing with a linearized problem we can neglect the 2nd order term. Thus dynamic pressure is simply:

$$\begin{aligned}
 p_d(x, z, t) &= -\rho \frac{\partial \phi}{\partial t} \\
 &= \frac{a\omega^2}{k} \rho f(z) \cos(\omega t - kx - \psi) = \rho \frac{\omega^2}{k} f(z) \eta(x, t) \\
 &= \rho g \eta(x, t) \frac{\cosh [k(z + H)]}{\cosh(kH)}
 \end{aligned}$$

Motion of a Fluid Particle



$$u = \frac{d\xi_p}{dt} \quad w = \frac{d\eta_p}{dt}$$

$$\xi_p(x,z,t) = a f(z) \cos(\omega t - kx + \psi)$$

$$\eta_p(x,z,t) = a f_1(z) \sin(\omega t - kx + \psi)$$

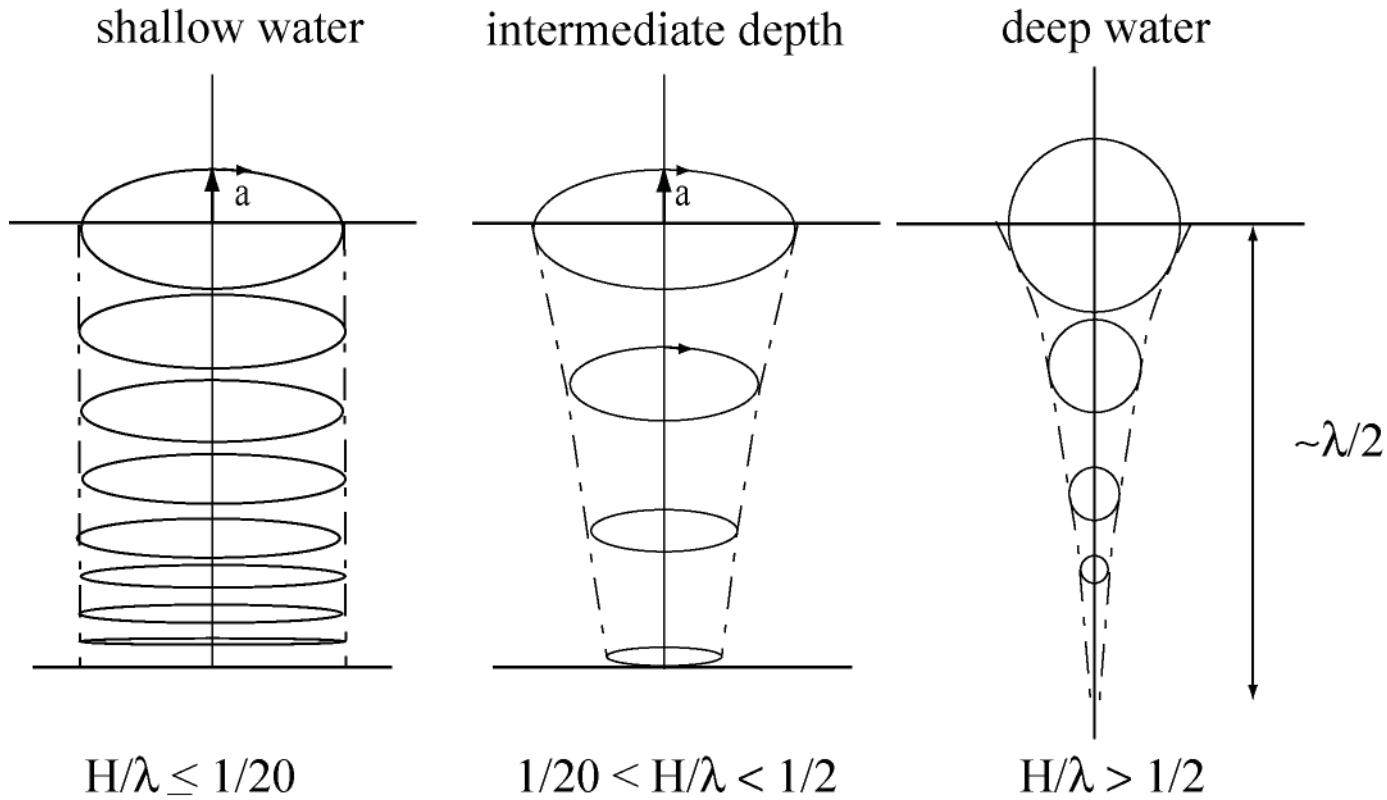
Elliptical
Orbit Path

$$\left[\frac{\xi_p}{f(z)} \right]^2 + \left[\frac{\eta_p}{f_1(z)} \right]^2 = a^2$$

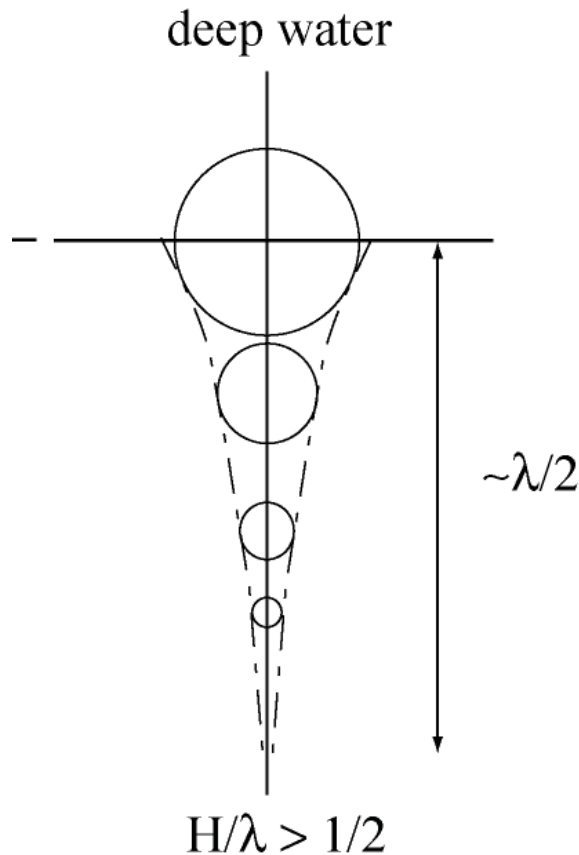
$$\left[\frac{\xi_p}{\frac{a \cosh k(z+H)}{\sinh kH}} \right]^2 + \left[\frac{\eta_p}{\frac{a \sinh k(z+H)}{\sinh kH}} \right]^2 = 1$$

Particle Orbits

Under the waves particles follow distinct orbits depending on whether the water is shallow, intermediate or deep. Water is considered deep when water depth is greater than one-half the wavelength of the wave.



Particle Orbits in Deep Water



$$H \rightarrow \infty \quad (kH \gg 1)$$

$\omega^2 = gk \Leftrightarrow$ dispersion relationship

$$f(z) \cong f_1(z) \cong e^{kz}$$

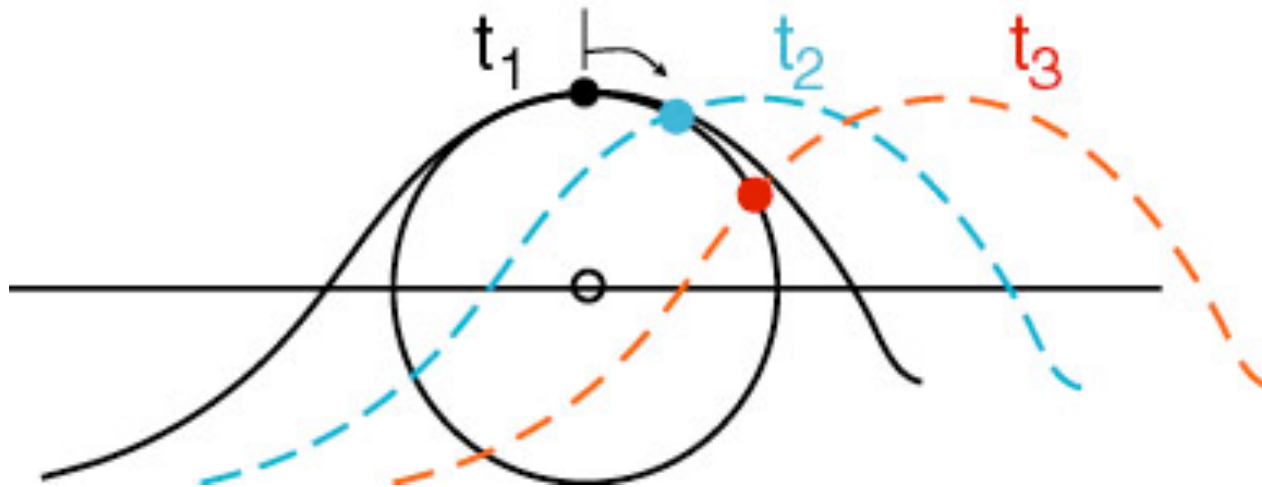
$$\xi_p^2 + \eta_p^2 = \left(a e^{kz} \right)^2$$

Circular orbits with
exponentially
decreasing radius

Particle motion extinct at $z \cong -\lambda/2$

at the free surface...

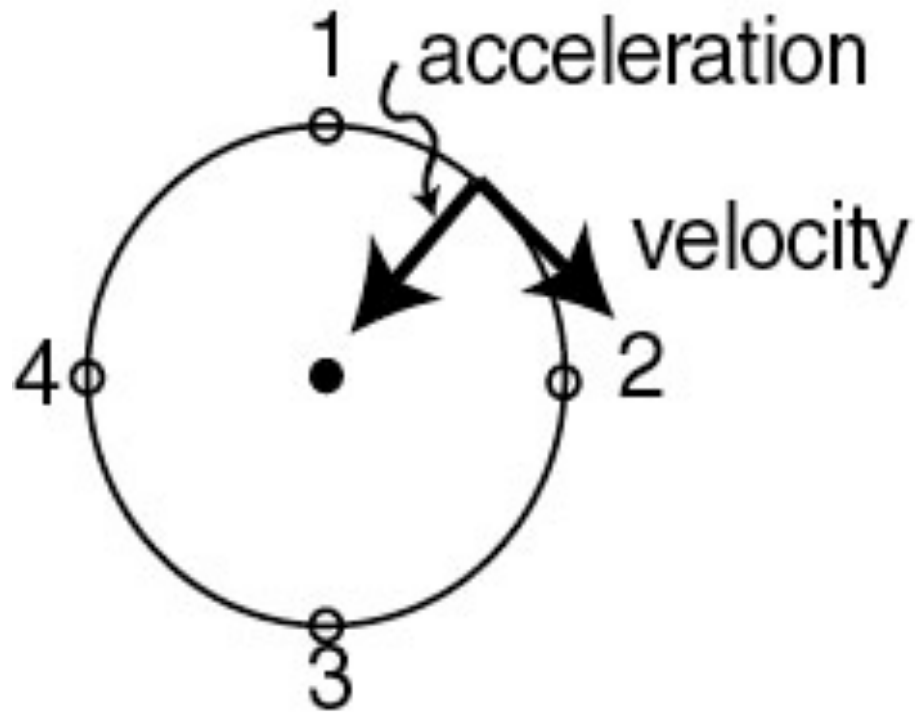
The intersection between the circle on which ξ_p and η_p lie and the elevation profile $\eta(x,t)$ define the location of the particle.



This applies at all depths, z :

$$\eta_p(x,z,t) = a e^{kz} \cos(\omega t - kx + \psi) = \eta(x,t) e^{kz}$$

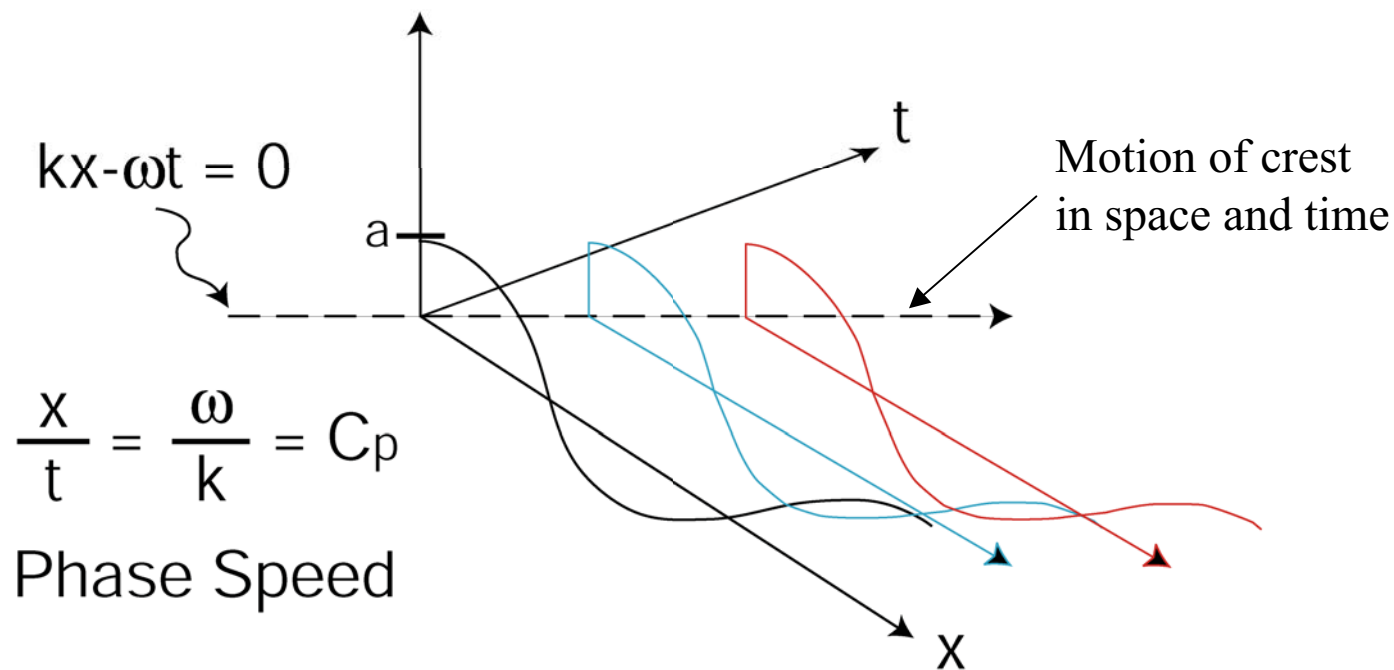
Particle acceleration and velocity



Phase Velocity

$$V_p = \frac{\lambda}{T} = \frac{\omega}{k} = \sqrt{\frac{g}{k} \tanh kH} \quad \text{Phase Velocity} = \text{speed of the wave crest}$$

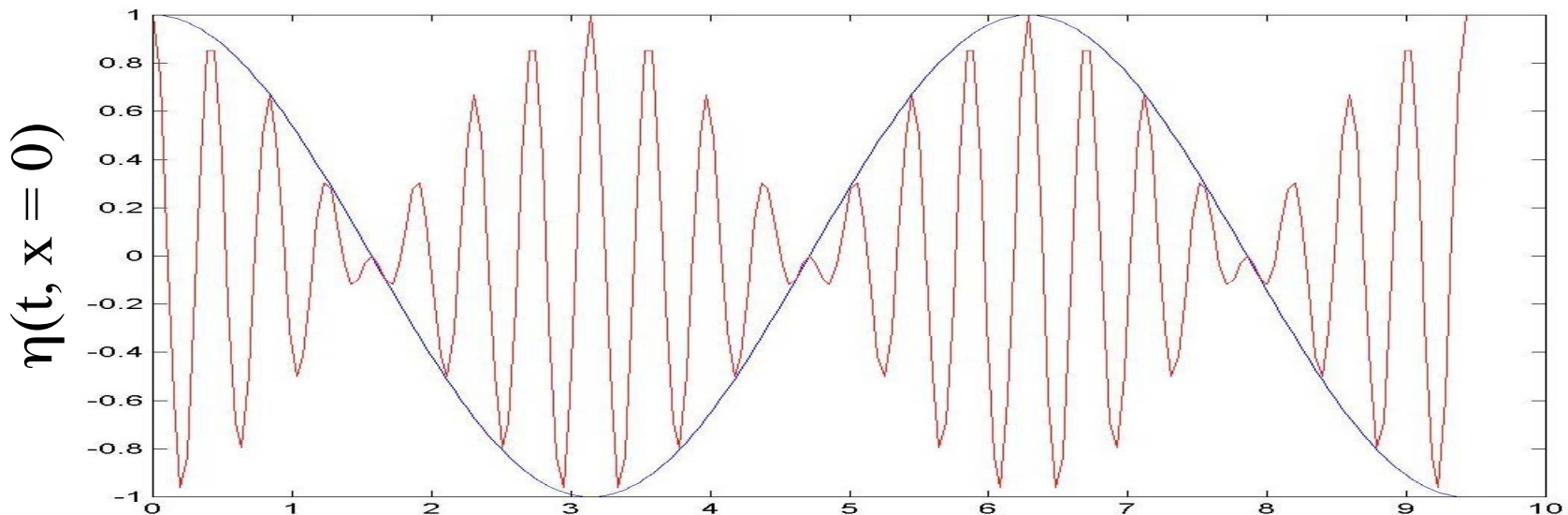
$$\eta(x,t) = a \cos(kx - \omega t + \psi) \quad \text{for } \psi = 0$$



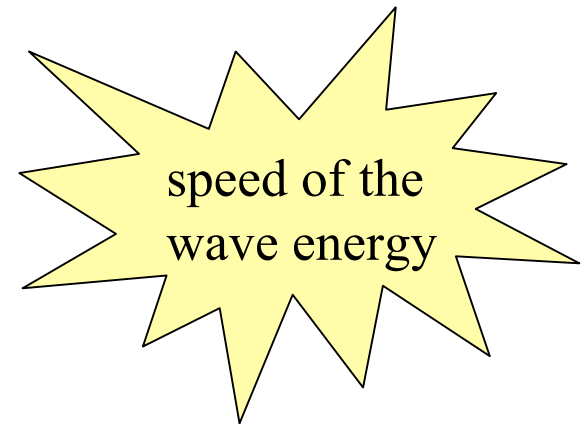
Group Velocity

Simple Harmonic Wave: $\eta(x,t) = a \cos(\omega t - kx)$

$$\begin{aligned}\eta(x,t) &= \lim_{\delta k, \delta \omega \rightarrow 0} \left\{ \frac{a}{2} \cos([\omega - \delta \omega]t - [k - \delta k]x) + \frac{a}{2} \cos([\omega + \delta \omega]t - [k + \delta k]x) \right\} \\ &= \lim_{\delta k, \delta \omega \rightarrow 0} \left\{ a \cos(\omega t - kx) \cos(\delta \omega t - \delta k x) \right\}\end{aligned}$$



Group Velocity



$$V_g = \frac{\delta\omega}{\delta k} = \frac{d\omega}{dk} \quad \omega^2 = gk \tanh(kH)$$

$$\frac{d}{dk} \{\omega^2\} = \frac{d}{dk} \{kg \tanh(kH)\}$$

$$2\omega \frac{d\omega}{dk} = g \tanh(kH) + \frac{kgH}{\cosh^2(kH)}$$

$$\frac{d\omega}{dk} = \frac{1}{2} \underbrace{\frac{g}{\omega} \tanh(kH)}_{\omega/k = V_p} \left\{ 1 + \frac{kH}{\sinh(kH) \cosh(kH)} \right\}$$

$$\therefore C_g = \frac{1}{2} C_p \left\{ 1 + \frac{kH}{\sinh kH \cosh kH} \right\}$$

Shallow water $H \rightarrow 0$

$$\omega = \sqrt{gHk} \quad C_g = C_p$$

Deep water $H \rightarrow \infty$

$$\omega^2 = kg \quad C_g = \frac{1}{2} C_p$$