MIT OpenCourseWare
http://ocw.mit.edu

### 6.641 Electromagnetic Fields, Forces, and Motion

Spring 2009

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.

| 6.641 - Electromagnetic Fields, Forces, and Motion | Spring 2005 |
| :--- | ---: |
| Final Review Packet |  |
| Prof. Markus Zahn |  |

## Contents

Practice Problems ..... 2
Problem 1 ..... 2
Problem 2 ..... 3
Problem 3 ..... 4
Problem 4 ..... 5
Problem 5 ..... 6
Final Exam 1998 Solutions ..... 7
Problem 1 ..... 7
Problem 2 ..... 9
Problem 3 ..... 11
Problem 4 ..... 13
Problem 5 ..... 15
Solutions to Two More Problems ..... 18
Problem 1 ..... 18
Problem 5 ..... 20
Final Exam 1995 Solutions ..... 22
Problem 1 ..... 22
Problem 5 ..... 24
Final Exam 2000 Solutions ..... 27
Problem 1 ..... 27
Problem 2 ..... 29
Problem 4 ..... 31
Problem 5 ..... 33

## Practice Problems

## Problem 1

A perfectly-conducting channel of height $D$ and width $2 W$ is divided into two free-space regions by a very thin perfectly-conducting slide as shown below. The $\hat{z}$-directed magnetic fields in the left and right regions are $H_{l}(t) \hat{z}$ and $H_{r}(t) \hat{z}$, respectively. The slide has a mass $M$ per unit length in the $\hat{z}$ direction, has a variable position $\xi(t)$, and makes a frictionless but perfectly-conducting contact with the channel.
(A) Assume that at $t=0, H_{l}=H_{l_{0}}, H_{r}=H_{r_{0}}$, and $\xi=\xi_{0}$. Determine $H_{l}(t)$ and $H_{r}(t)$ in terms of $H_{l_{0}}, H_{r_{0}}, \xi_{0}$, and $\xi(t)$.
(B) The very thin slide supports a surface current $K \hat{y}$ which separates $H_{l} \hat{z}$ and $H_{r} \hat{z}$. This current interacts with the neighboring magnetic fields to produce a force $F \hat{x}$ on the slide per unit length in the $\hat{z}$ direction. Evaluate $F$.
(C) Use the results of (B) to find a function $V(\xi)$ so that

$$
\frac{d}{d t}\left(\frac{M}{2}\left(\frac{d \xi(t)}{d t}\right)^{2}+V(\xi)\right)=0
$$

(D) At $t=0, \frac{d \xi}{d t}=0$. Determine the velocity of the slide when it first reaches $\xi(t)=0$.


Figure 1: A perfectly-conducting channel with a perfectly conducting slide.

## Problem 2

A conducting plate of thickness $\Delta$, permeability $\mu_{0}$ and conductivity $\sigma$ moves with velocity $U$ in the $\hat{z}$ direction between two perfectly-permeable plates as shown below. At $z=0, \bar{B}$ is constrained to be Real $\left\{B_{0} e^{j \omega t}\right\} \hat{x}$ by exciter coils. The perfectly-permeable plates confine $\bar{B}$ to the region $0 \leq z \leq L$ so that $\bar{B}=0 \hat{x}$ at $z=L$. Within the region $0 \leq z \leq L, \bar{B}$ is approximated by $\bar{B}=B_{x}(z, t) \hat{x}$. Ignore fringing fields.
(A) Derive a differential equation for $B_{x}$ in the conducting slab for $0 \leq z \leq L$.
(B) Determine $B_{x}$ for $0 \leq z \leq L$.
(C) Determine the external force $f$ needed to pull the plate in the $\hat{z}$ direction at velocity $U$.


Figure 2: A conducting plate moving between infinitely permeable plates. (Image by MIT OpenCourseWare.)

## Problem 3

A simplified model of a Van de Graaff generator is shown below. A belt with permittivity $\epsilon$, conductivity $\sigma$, thickness $\delta$, and width $W$ travels to the right with velocity $U$. At $x=0$, a charge source maintains the charge density $\rho_{0}$ on the belt. At $x=l$, a charge collector collects all the charge off the belt. An external resistance $R$ is connected from the charge collector to the charge source. Determine the current $i$ through the resistor when the generator is in steady state.


Figure 3: A simplified Van de Graaff generator.

## Problem 4

A pair of grounded perfectly-conducting plates of infinite extent in the $\hat{y}$ and $\hat{z}$ directions are located at $x=\Delta$ and $x=-\Delta$ as shown below. A fluid having permittivity $\epsilon$ and conductivity $\sigma$ flows with uniform velocity $U$ in the $\hat{z}$ direction between the plates. At $t=0$, the fluid has a charge distribution given by

$$
\rho(x, y, z)= \begin{cases}\rho_{0} \sin \left(\frac{\pi x}{\Delta}\right) e^{-k y^{2}} & |z| \leq \delta \\ 0 & |z|>\delta\end{cases}
$$

Determine $\rho(x, y, z, t)$ between the plates for $t>0,|x| \leq \Delta$, and all $y$ and $z$.


Figure 4: A pair of grounded perfectly-conducting plates enclose a moving conductor (Image by MIT OpenCourseWare.)

## Problem 5

A thin sheet having effective surface conductivity $\sigma_{0}$ moves in the $\hat{z}$ direction with velocity $U$ as shown below. The sheet is symmetrically located at a distance $\Delta$ between two potential sources. The potential sources are symmetrically excited as traveling waves with frequency $\omega$ and wave number $k$. Assume $k \Delta \ll 1$ and make appropriate assumptions.
(A) Find the electric field components $E_{x}$ and $E_{z}$ just above and below the thin sheet.
(B) Find the free surface charge in the thin sheet.
(C) Find the spatially and temporally averaged $\hat{z}$-directed force per $y-z$ area which acts on the sheet.


Figure 5: A thin sheet (Image by MIT OpenCourseWare.)

## Final Exam 1998 Solutions

## Problem 1



Figure 6: A magnetic circuit

In the magnetic circuit shown above, a current $I$ flows in the $N$ turn coil which is mounted on a material of infinite magnetic permeability $(\mu \rightarrow \infty)$ except for a thin gap of width $a$ and height $b$ which has finite magnetic permeability $\mu_{1}$. The lower plate has infinite magnetic permeability $(\mu \rightarrow \infty)$ and is at a distance $x$ below the upper assembly. The magnetic materials are surrounded by free space with magnetic permeability $\mu_{0}$. The entire system has depth $D$.
(A) Neglecting fringing field effects, find the magnetic field $H_{0}$ in the air gap and $H_{1}$ in the thin section of the upper magnetic part.
Solution:

$$
\begin{aligned}
H_{0} 2 x+H_{1} a & =N I \\
\mu_{0} H_{0} s \not \varnothing & =\mu_{1} H_{1} b \not \varnothing \\
H_{1} & =\frac{\mu_{0} H_{0} s}{\mu_{1} b}
\end{aligned}
$$

$$
\begin{aligned}
H_{0}\left[2 x+\frac{\mu_{0} s a}{\mu_{1} b}\right]=N I \Rightarrow H_{0} & =\frac{N I \mu_{1} b}{2 \mu_{1} b x+\mu_{0} s a} \\
H_{1} & =\frac{N I \mu_{0} s}{2 \mu_{1} b x+\mu_{0} s a}
\end{aligned}
$$

(B) Find the self-inductance of the $N$ turn coil.

Solution:

$$
\begin{aligned}
L & =\frac{N \Phi}{I}, \Phi=\mu_{0} H_{0} s D=\mu_{1} H_{1} b D \\
& =\frac{N^{2} \mu_{0} \mu_{1} b s D}{2 \mu_{1} b x+\mu_{0} s a}
\end{aligned}
$$

(C) Find the total magnetic energy stored in the system.

## Solution:

$$
W_{M}=\frac{1}{2} L I^{2}=\frac{1}{2} \frac{(N I)^{2} \mu_{0} \mu_{1} b s D}{2 \mu_{1} b x+\mu_{0} s a}
$$

Alternate Method:

$$
\begin{aligned}
W_{M} & =\frac{1}{\not 2} \mu_{0} H_{0}^{2} x s D(\not 2)+\frac{1}{2} \mu_{1} H_{1}^{2} a b D \\
& =H_{0}^{2}\left[\mu_{0} x s D+\frac{1}{2} \mu_{1} a b D\left(\frac{\mu_{0} s}{\mu_{1} b}\right)^{2}\right] \\
& =\frac{H_{0}^{2} D}{\left(\mu_{1} b\right)^{2}}\left[\mu_{0} x s\left(\mu_{1} b\right)^{2}+\frac{1}{2} \mu_{1} a b\left(\mu_{0} s\right)^{2}\right] \\
& =\frac{H_{0}^{2} D}{\left(\mu_{1} b\right)^{2}} \mu_{0} \mu_{1} b s\left[x \mu_{1} b+\frac{1}{2} \mu_{0} a s\right] \\
& =\frac{(N I)^{2}\left(\mu_{1}^{\not ㇒} b^{2}\right) D}{\left(\mu_{1} b\right)^{2}\left(2 \mu_{1} b x+\mu_{0} s a\right)^{2}} \mu_{0} \mu_{1} \not b s\left[x \mu_{1} b+\frac{1}{2} \mu_{0} a s\right] \\
& =\frac{\frac{1}{2}(N I)^{2} \mu_{1} \mu_{0} b s D}{\left(2 \mu_{1} b x_{+} \mu_{0} s a\right)}
\end{aligned}
$$

(D) Find the magnetic force on the moveable lower plate as a function of $x$, material properties, $N$, $I$, and geometric dimensions.

## Solution:

$$
\begin{aligned}
f_{x} & =\frac{1}{2} I^{2} \frac{d L}{d x} \\
& =-\frac{1}{\mathscr{2}} \frac{I^{2} N^{2} \mu_{0} \mu_{1} b s D}{\left(2 \mu_{1} b x+\mu_{0} s a\right)^{2}} \not 2 \mu_{1} b \\
& =-\frac{(N I)^{2} \mu_{0} \mu_{1}^{2} b^{2} s D}{\left(2 \mu_{1} b x+\mu_{0} s a\right)^{2}}
\end{aligned}
$$

## Problem 2



Figure 7: A sphere with a point magnetic dipole at its center

A point magnetic dipole with moment $\bar{m}=m_{0} \bar{i}_{z}$ is located at the center of a sphere of radius $R$. The sphere has finite magnetic permeability $\mu$ and the sphere is surrounded by free space with magnetic permeability $\mu_{0}$. There is no free surface current on the $r=R$ interface.
(A) What boundary conditions must be satisfied by the magnetic scalar potential and/or magnetic field at $r=0, r=R$, and $r=\infty$ ?

## Solution:

$$
\begin{aligned}
\chi_{m}(r=0) & =\frac{m_{0}}{4 \pi} \frac{\cos \theta}{r^{2}}, \chi_{m}(r \rightarrow \infty)=0 \\
H_{\theta}\left(r=R_{-}\right) & =H_{\theta}\left(r=R_{+}\right), B_{r}\left(r=R_{-}\right)=B_{r}\left(r=R_{+}\right) \Rightarrow \mu H_{r}\left(r=R_{-}\right)=\mu_{0} H_{r}\left(r=R_{+}\right)
\end{aligned}
$$

(B) Find the magnetic field $\bar{H}$ inside and outside the sphere.

## Solution:

$$
\begin{aligned}
& \chi_{m}= \begin{cases}\frac{m_{0}}{4 \pi} \frac{\cos \theta}{r^{2}}+A r \cos \theta & 0<r<R \\
\frac{C}{r^{2}} \cos \theta & r>R\end{cases} \\
& \bar{H}=-\nabla \chi_{m}=-\left[\frac{\partial \chi_{m}}{\partial r} \overline{i_{r}}+\frac{1}{r} \frac{\partial \chi_{m}}{\partial \theta} \overline{i_{\theta}}\right] \\
& = \begin{cases}\frac{m_{0}}{4 \pi r^{3}}\left(2 \cos \theta \overline{i_{r}}+\sin \theta \overline{i_{\theta}}\right)-A\left[\cos \theta \overline{i_{r}}-\sin \theta \overline{i_{\theta}}\right] & 0<r<R \\
\frac{C}{r^{3}}\left(2 \cos \theta \overline{i_{r}}+\sin \theta \overline{i_{\theta}}\right) & r>R\end{cases} \\
& H_{\theta}\left(r=R_{-}\right)=H_{\theta}\left(r=R_{+}\right) \Rightarrow \frac{C}{R^{3}}=\frac{m_{0}}{4 \pi R^{3}}+A \\
& \mu H_{r}\left(r=R_{-}\right)=\mu_{0} H_{r}\left(r=R_{+}\right) \Rightarrow \mu\left[\frac{2 m_{0}}{4 \pi R^{3}}-A\right]=\frac{2 \mu_{0} C}{R^{3}} \\
& \frac{m_{0}}{4 \pi R^{3}}+A=\frac{C}{R^{3}} \\
& \frac{2 m_{0}}{4 \pi R^{3}}-A=\frac{2 \mu_{0}}{\mu R^{3}} C \\
& \frac{C}{R^{3}}\left(1+\frac{2 \mu_{0}}{\mu}\right)=\frac{3 m_{0}}{4 \pi R^{3}} \Rightarrow \frac{C}{R^{3}}=\frac{3 m_{0}}{4 \pi R^{3}\left(1+\frac{2 \mu_{0}}{\mu}\right)} \\
& A=\frac{C}{R^{3}}-\frac{m_{0}}{4 \pi R^{3}}=\frac{m_{0}}{4 \pi R^{3}}\left(\frac{3}{1+\frac{2 \mu_{0}}{\mu}}-1\right)=\frac{m_{0}}{4 \pi R^{3}}\left(\frac{2\left(1-\frac{\mu_{0}}{\mu}\right)}{\left(1+2 \frac{\mu_{0}}{\mu}\right)}\right) \\
& \bar{H}=\left\{\begin{array}{l}
\frac{m_{0}}{4 \pi r^{3}}\left[2 \cos \theta \overline{i_{r}}+\sin \theta \overline{i_{\theta}}\right]-\frac{m_{0}}{2 \pi R^{3}} \frac{\left(1-\frac{\mu_{0}}{\mu}\right)}{1+\frac{2 \mu_{0}}{\mu}}\left(\cos \theta \overline{i_{r}}-\sin \theta \overline{\bar{i}_{\theta}}\right) \quad 0<r<R \\
\frac{3 m_{0}}{4 \pi r^{3}} \frac{\left(2 \cos \theta \overline{i_{r}}+\sin \theta \overline{i_{\theta}}\right)}{\left(1+\frac{\mu_{0}}{\mu}\right)}
\end{array}\right.
\end{aligned}
$$

(C) What is the effective magnetic dipole moment of the sphere seen by an observer for $r>R$ ?

Solution:

$$
\frac{m_{\mathrm{eff}}}{4 \pi}=C \Rightarrow m_{\mathrm{eff}}=4 \pi \frac{3 m_{0}}{4 \pi\left(1+\frac{2 \mu_{0}}{\mu}\right)} \Rightarrow m_{\mathrm{eff}}=\frac{3 m_{0}}{1+\frac{2 \mu_{0}}{\mu}}
$$

## Problem 3



Figure 8: A coaxial cylindrical capacitor (Image by MIT OpenCourseWare.)

A coaxial cylindrical capacitor is dipped into a linearly polarizable fluid with dielectric permittivity $\epsilon$ and mass density $\rho_{m}$. Gravity is directed downwards.

When voltage $V_{0}$ is applied, the dielectric fluid is pulled into the coaxial capacitor to a height $x$ above the fluid level outside the cylinders. If $V_{0}=0$, the fluid level within the cylinders is a distance $s$ from the lower end of the cylinder. There is no free volume charge in the system .
(A) Neglecting fringing field effects, what is the electric field, magnitude and direction, between the cylinders $(a<r<b)$ as a function of $r$ in both the upper free space region and in the lower dielectric fluid?

## Solution:

$\nabla \cdot \bar{E}=\frac{1}{r} \frac{d}{d r}\left(r E_{r}\right)=0 \Rightarrow E_{r}=\frac{A}{r}$
$\int_{a}^{b} E_{r} d r=A \ln \frac{b}{a}=V_{0} \Rightarrow A=\frac{V_{0}}{\ln \frac{b}{a}}$
$E_{r}=\frac{V_{0}}{r \ln \frac{b}{a}} \quad$ (In both regions between cylinders)
Note that tangential $E$ is continuous at the dielectric interface

## (B) What is the capacitance as a function of $x$ ?

## Solution:

In free space region: $D_{r}=\frac{\epsilon_{0} V_{0}}{r \ln \frac{b}{a}}$.

In dielectric fluid: $D_{r}=\frac{\epsilon V_{0}}{r \ln \frac{b}{a}}$.
Free surface charge on $\mathrm{r}=$ a surface:

$$
\begin{aligned}
q & =\left.\epsilon_{0} E_{r}\right|_{a} 2 \pi a(l-x-s)+\left.\epsilon E_{r}\right|_{a} 2 \pi a(x+s) \\
& =\left.E_{r}\right|_{a} 2 \pi a\left(\epsilon_{0}(l-x-s)+\epsilon(x+s)\right) \\
& =\frac{V_{0}}{\not 4 \ln \frac{b}{a}} 2 \pi \not \subset\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right] \\
& =\frac{2 \pi V_{0}}{\ln \frac{b}{a}}\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right] \\
C & =\frac{q}{V_{0}}=\frac{2 \pi\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right]}{\ln \frac{b}{a}}
\end{aligned}
$$

(C) What is the total electric energy stored in the system?

Solution:

$$
W_{E}=\frac{1}{2} C V_{0}^{2}=\frac{\pi\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right]}{\ln \frac{b}{a}} V_{0}^{2}
$$

Alternate Method:

$$
\begin{aligned}
W_{E} & =\int_{V} \frac{1}{2} \epsilon E^{2} d V=\int_{r=a}^{b} \int_{\Phi=0}^{2 \pi} \int_{z=0}^{l} \frac{1}{2} \epsilon E^{2} r d r d \Phi d z \\
W_{E} & =\int_{r=a}^{b} \frac{1}{2} E_{r}^{2} r d r\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right] 2 \pi \\
& =\frac{\not 2 \pi}{2} \frac{\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right] V_{0}^{2}}{\left[\ln \left(\frac{b}{a}\right)\right]^{2}} \int_{r=a}^{b} \frac{d r}{r} \\
& =\frac{\pi\left[\epsilon_{0}(l-x-s)+\epsilon(x+s)\right] V_{0}^{2}}{\ln \frac{b}{a}}
\end{aligned}
$$

(D) How high will the dielectric fluid rise when a voltage $V_{0}$ is applied?

Solution:

$$
\begin{aligned}
& f_{x}=\frac{1}{2} V_{0}^{2} \frac{d C}{d x}=\frac{1}{\not 2} \frac{V_{0}^{2} \not 2 \pi\left[\epsilon-\epsilon_{0}\right]}{\ln \frac{b}{a}}=\rho_{m} g \pi\left(b^{2}-a^{2}\right) x \\
& x=\frac{V_{0}^{2}\left(\epsilon-\epsilon_{0}\right)}{\ln \frac{b}{a} \rho_{m} g\left(b^{2}-a^{2}\right)}
\end{aligned}
$$

## Problem 4



Figure 9: Two lossy dielectrics
Two lossy dielectrics with respective dielectric permittivities $\epsilon_{1}$ and $\epsilon_{2}$ and respective ohmic conductivities $\sigma_{1}$ and $\sigma_{2}$ are superposed within a short-circuited capacitor. At $t=0$ there is a free surface charge density of $\sigma_{s 0} \frac{C}{m^{2}}$ on the interface between the dielectrics. Neglect fringing field effects. The free volume charge density at time $t=0$ is zero in both dielectrics.
(A) Find the electric fields $E_{1}(t=0)$ and $E_{2}(t=0)$ in both lossy dielectrics at time $t=0$.

## Solution:

$$
\begin{aligned}
& \rho_{f}(t)=0 \text { in both dielectrics } \Rightarrow \nabla \cdot \bar{E}_{1}=\nabla \cdot \bar{E}_{2}=0 \Rightarrow E_{1}=E_{1}(t), E_{2}=E_{2}(t) \\
& \int_{x=0}^{a+b} E d x=\int_{x=0}^{b} E_{2} d x+\int_{x=b}^{a+b} E_{1} d x=E_{2} b+E_{1} a=0 \Rightarrow E_{2}=-\frac{E_{1} a}{b}
\end{aligned}
$$

at $t=0$ :

$$
\begin{aligned}
& \epsilon_{1} E_{1}-\epsilon_{2} E_{2}=\sigma_{s 0} \\
& E_{1}\left[\epsilon_{1}+\frac{\epsilon_{2} a}{b}\right]=\sigma_{s 0} \\
& E_{1}=\frac{\sigma_{s 0} b}{\epsilon_{1} b+\sigma_{2} a}, E_{2}=-\frac{E_{1} a}{b}=-\frac{\sigma_{s 0} a}{\epsilon_{1} b+\epsilon_{2} a}
\end{aligned}
$$

(B) Find the electric fields $E_{1}(t)$ and $E_{2}(t)$ in both lossy dielectrics as a function of time.

Solution:

$$
\begin{aligned}
& \sigma_{1} E_{1}-\sigma_{2} E_{2}+\frac{d}{d t}\left[\epsilon_{1} E_{1}-\epsilon_{2} E_{2}\right]=0 \\
& E_{1}\left[\sigma_{1}+\frac{\sigma_{2} a}{b}\right]+\left(\epsilon_{1}+\frac{\epsilon_{2} a}{b}\right) \frac{d E_{1}}{d t}=0 \\
& E_{1}=E_{1}(t=0) e^{-\frac{t}{\tau}} ; \tau=\frac{\epsilon_{1} b+\epsilon_{2} a}{\sigma_{1} b+\sigma_{2} a} \\
& E_{1}=\frac{\sigma_{s 0} b}{\epsilon_{1} b+\epsilon_{2} a} e^{-\frac{t}{\tau}} \\
& E_{2}=-\frac{E_{1} a}{b}=-\frac{\sigma_{s 0} a}{\epsilon_{1} b+\epsilon_{2} a} e^{-\frac{t}{\tau}}
\end{aligned}
$$

(C) Find the free surface charge density $\sigma_{s}(t)$ on the interface as a function of time.

Solution:

$$
\sigma_{s}(t)=\epsilon_{1} E_{1}-\epsilon_{2} E_{2}=E_{1}\left(\epsilon_{1}+\frac{\epsilon_{2} a}{b}\right)=\sigma_{s 0} e^{-\frac{t}{\tau}}
$$

(D) Find the short circuit current $i(t)$ that flows in the wire short-circuiting the two electrodes as a function of time.

## Solution:

$$
\begin{aligned}
\frac{i(t)}{l d} & =\sigma_{2} E_{2}+\epsilon_{2} \frac{d E_{2}}{d t}=\sigma_{1} E_{1}+\epsilon_{1} \frac{d E_{1}}{d t} \\
& =\left(\sigma_{1}-\frac{\epsilon_{1}}{\tau}\right) E_{1} \\
& =\left(\sigma_{1}-\frac{\epsilon_{1}}{\left(\epsilon_{1} b+\sigma_{2} a\right)}\left(\sigma_{1} b+\sigma_{2} a\right)\right) E_{1} \\
& =\left(\frac{\sigma_{1} \epsilon_{1} b+\sigma_{1} \epsilon_{2} a-\epsilon_{1} \sigma_{1} b-\epsilon_{1} \sigma_{2} a}{\epsilon_{1} b+\epsilon_{2} a}\right) E_{1} \\
& =\frac{a\left(\sigma_{1} \epsilon_{2}-\epsilon_{1} \sigma_{2}\right)}{\left(\epsilon_{1} b+\epsilon_{2} a\right)^{2}} \sigma_{s 0} b e^{-\frac{t}{\tau}} \\
i(t) & =\frac{a b \sigma_{s 0}\left(\sigma_{1} \epsilon_{2}-\epsilon_{1} \sigma_{2}\right) l d}{\left(\epsilon_{1} b+\epsilon_{2} a\right)^{2}} e^{-\frac{t}{\tau}}
\end{aligned}
$$

## Problem 5



Depth D


Figure 10: A lossy transmission line

A lossy transmission line is composed of perfectly conducting parallel plates enclosing a lossy medium with dielectric permittivity $\epsilon$, magnetic permeability $\mu$, and ohmic conductivity $\sigma$. The governing equations for the voltage $v(z, t)$ and current $i(z, t)$ along the transmission line are

$$
\begin{aligned}
& \frac{\partial i}{\partial z}=-C \frac{\partial v}{\partial t}-G v \\
& \frac{\partial v}{\partial z}=-L \frac{\partial i}{\partial t}
\end{aligned}
$$

Where $C$ is the capacitance per unit length, $G$ is the conductance per unit length, and $L$ is the inductance per unit length. The transmission line is short circuited at $z=0$ and is driven by a voltage source at $z=-l, v(z=-l, t)=V_{0} \cos (\omega t)$.
(A) What are $C, G$, and $L$ in terms of $\epsilon, \mu, \sigma, l, D$ and $s$ ?

## Solution:

$$
C=\frac{\epsilon d}{s}, L=\frac{\mu s}{d}, G=\frac{\sigma d}{s} \quad\left(R C=\frac{\epsilon}{\sigma} \Rightarrow G=\frac{1}{R}=\frac{\sigma C}{\epsilon}\right)
$$

(B) In the sinusoidal steady state the voltage and current can be written in the form

$$
\begin{aligned}
v(z, t) & =\operatorname{Re}\left[\hat{v}(z) e^{j \omega t}\right] \\
i(z, t) & =\operatorname{Re}\left[\hat{i}(z) e^{j \omega t}\right]
\end{aligned}
$$

Find $\hat{v}(z)$ for this problem.

## Solution:

$\frac{d \hat{i}}{d z}=-(G+C j \omega) \hat{v}$
$\frac{d \hat{v}}{d z}=-L j \omega \hat{i} \Rightarrow \hat{i}=-\frac{1}{L j \omega} \frac{d \hat{v}}{d z}$
$\frac{1}{L j \omega} \frac{d^{2} \hat{v}}{d z^{2}}=+(G+C j \omega) \hat{v}$
$\frac{d^{2} \hat{v}}{d z^{2}}=\left(G L j \omega-L C \omega^{2}\right) \hat{v}$
$\hat{v}(z)=A e^{j p z} \Rightarrow-p^{2}=G L j \omega-L C \omega^{2}$

$$
\begin{aligned}
& p= \pm \sqrt{L C \omega^{2}-G L j \omega} \\
& p= \pm p_{0}, p_{0}=\sqrt{L C \omega^{2}-G L j \omega}
\end{aligned}
$$

$\hat{v}(z)=A_{1} e^{j p_{0} z}+A_{2} e^{-j p_{0} z}$
$\hat{v}(z=0)=0=A_{1}+A_{2}$
$\hat{v}(z=-l)=V_{0}=A_{1} e^{-j p_{0} l}+A_{2} e^{j p_{0} l}=A_{1}\left(e^{-j p_{0} l}-e^{j p_{0} l}\right)=-2 j A_{1} \sin p_{0} l$
$A_{1}=-A_{2}=-\frac{V_{0}}{2 j \sin p_{0} l}$
$\hat{v}(z)=-\frac{V_{0}}{2 j \sin p_{0} l}\left(e^{j p_{0} z}-e^{-j p_{0} z}\right)=-\frac{V_{0} \sin p_{0} z}{\sin p_{0} l}$
(C) Find $\hat{i}(z)$ for this problem.

Solution:
$\hat{i}(z)=-\frac{1}{L j \omega} \frac{d \hat{v}}{d z}=-\frac{1}{L j \omega}\left(-\frac{V_{0} p_{0} \cos p_{0} z}{\sin p_{0} l}\right)=\frac{V_{0} p_{0}}{L j \omega} \frac{\cos p_{0} z}{\sin p_{0} l}$
(D) Now, assuming $G=0$ and neglecting fringing field effects, find the Poynting vector $\bar{S}=\bar{E} \times \bar{H}$ as a function of time and position $z$ everywhere along the transmission line for $-l \leq z \leq 0$.

## Solution:

$$
\begin{gathered}
G=0 \Rightarrow p_{0}=\omega \sqrt{L C} \quad(\text { real }), v(z, t)=\operatorname{Re} \hat{v}(z) e^{j \omega t}-\frac{V_{0} \sin p_{0} z}{\sin p_{0} l} \cos \omega t \\
i(z, t)=R e\left[+\frac{V_{0} p_{0}}{L j \omega} \frac{\cos p_{0} z}{\sin p_{0} l} e^{j \omega t}\right]=\frac{V_{0} p_{0}}{L \omega} \frac{\cos p_{0} z}{\sin p_{0} l} \sin \omega t=+V_{0} \sqrt{\frac{C}{L}} \frac{\cos p_{0} z}{\sin p_{0} l} \sin \omega t \\
E_{x}=\frac{v(z, t)}{s}, H_{y}=\frac{i(z, t)}{d} \Rightarrow \bar{S}=\bar{E} \times \bar{H}=E_{x} H_{y} \bar{i}_{z}=\frac{v(z, t) i(z, t)}{s d} \overline{i_{z}}=\frac{-V_{0}^{2} \sqrt{\frac{C}{L}} \sin p_{0} z \cos p_{0} z \sin \omega t \cos \omega t}{s d \sin ^{2} p_{0} l} i
\end{gathered}
$$

## Solutions to Two More Problems

## Problem 1



Figure 11: A magnetic circuit with a stationary yoke

A magnetic circuit has a stationary yoke with infinite magnetic permeability with a voltage source $v(t)=$ $V_{0} \cos \omega t$ exciting an $N$-turn perfectly conducting coil. In the air gap of the magnetic yoke of height $s$ there is an infinitely magnetically permeable tapered wedge of height $a(a<s)$ whose width decreases from $w_{1}$ to $w_{2}$. The bottom surface of the wedge is a distance $x$ above the lower surface of the magnetic yoke. The system has depth $D$. Assume that both air gaps are sufficiently small to neglect fringing fields.
(A) What is the total magnetic flux $\lambda(t)$ linking the $N$-turn coil?

## Solution:

$$
v=V_{0} \cos \omega t=\frac{d \lambda}{d t} \Rightarrow \lambda=\frac{V_{0}}{\omega} \sin \omega t
$$

(B) What are the magnetic fields, $\bar{H}_{1}(t)$ and $\bar{H}_{2}(t)$, in the air gaps in terms of $\lambda(t)$, $\mu_{0}$, and geometric parameters?

## Solution:

$$
\begin{aligned}
& \mu_{0} H_{1} w_{1} D=\mu_{0} H_{2} w_{2} D=\frac{\lambda}{N} \\
& H_{1}=\frac{\lambda}{N \mu_{0} w_{1} D} \\
& H_{2}=\frac{\lambda}{N \mu_{0} w_{2} D}
\end{aligned}
$$

(C) What is the self-inductance $L(x)$ of the $N$ turn coil as a function of the distance $x, \mu_{0}$, and geometric parameters?

## Solution:

$$
\begin{aligned}
\oint \bar{H} \cdot \overline{d l} & =N i=H_{1}(s-a-x)+H_{2} x \\
& =\frac{\lambda}{N \mu_{0} D}\left(\frac{s-a-x}{w_{1}}+\frac{x}{w_{2}}\right)
\end{aligned}
$$

$$
L(x)=\frac{\lambda}{i}=\frac{N^{2} \mu_{0} D}{\left[\frac{s-a-x}{w_{1}}+\frac{x}{w_{2}}\right]}
$$

(D) What is the $x$-directed force on the tapered wedge in terms of $\lambda(t), \mu_{0}$, and geometric parameters?

## Solution:

$$
\begin{aligned}
f_{x} & =-\frac{1}{2} \lambda^{2} \frac{d}{d x}\left[\frac{1}{L(x)}\right] \\
& =-\frac{\lambda^{2}}{2} \frac{d}{d x} \frac{\left[\frac{s-a-x}{w_{1}}+\frac{x}{w_{2}}\right]}{N^{2} \mu_{0} D} \\
& =-\frac{\lambda^{2}}{2 N^{2} \mu_{0} D}\left[\frac{1}{w_{2}}-\frac{1}{w_{1}}\right]
\end{aligned}
$$

## Problem 5



Figure 12: A current sheet of infinite extent
A $z$ directed current sheet of infinite extent in the $y$ and $z$ directions is located at $x=0$ and varies with time as

$$
\bar{K}(x=0, y, z, t)=\bar{i}_{z} K_{0} \cos \omega t
$$

This current sheet is located at the interface separating a material of infinite magnetic permeability $(\mu \rightarrow \infty)$ for $-\infty<x<0$ and a material of finite magnetic permeability $\mu$ and finite ohmic conductivity $\sigma$ for $0<x<\infty$. Note that because the current sheet has no variation with $y$ or $z$, the magnetic field does not depend on the $y$ or $z$ coordinates.
(A) Find the magnitude and direction of the magnetic field $\bar{H}(x, t)$ everywhere.

Solution:

$$
\begin{aligned}
& H_{y}(x, t)=\operatorname{Re} \hat{H}_{y}(x) e^{j \omega t} \\
& \begin{aligned}
\hat{H}_{y}(x=0) & =K_{0} \Rightarrow \hat{H}_{y}(x)=K_{0} e^{-\frac{(1+j) x}{\delta}}, \delta=\sqrt{\frac{2}{\omega \mu \sigma}} \\
H_{y}(x, t) & =\operatorname{Re} K_{0} e^{-\frac{x}{\delta}} e^{-\frac{j x}{\delta}} e^{j \omega t} \\
& =K_{0} e^{-\frac{x}{\delta}} \cos \left(\omega t-\frac{x}{\delta}\right) \quad x>0
\end{aligned}
\end{aligned}
$$

$$
H_{y}(x, t)=0 \quad x<0
$$

(B) Find the volume current density $\bar{J}(x, t)$ everywhere.

Solution:

$$
\begin{aligned}
& \nabla \times \bar{H}=\bar{J} \Rightarrow \frac{\partial H_{y}}{\partial x}=J_{z}, J_{z}=0, x<0 \\
& J_{z}=\frac{\partial H_{y}}{\partial x}=\frac{K_{0} e^{-\frac{x}{\delta}}}{\delta}\left[-\cos \left(\omega t-\frac{x}{\delta}\right)+\sin \left(\omega t-\frac{x}{\delta}\right)\right]
\end{aligned}
$$

(C) Find the power flow density, $\bar{S}=\bar{E} \times \bar{H}$, everywhere.

Solution:

$$
\underline{x>0} \text { : }
$$

$$
\bar{S}=\bar{E} \times \bar{H}=\frac{\bar{J}}{\sigma} \times \bar{H}=\frac{J_{z}}{\sigma} H_{y} \overline{i_{z}} \times \overline{i_{y}}
$$

$$
=-\frac{J_{z}}{\sigma} H_{y} \overline{i_{x}}
$$

$$
=-\frac{K_{0}^{2} e^{-\frac{2 x}{\delta}}}{\delta \sigma}\left[-\cos \left(\omega t-\frac{x}{\delta}\right)+\sin \left(\omega t-\frac{x}{\delta}\right)\right] \cos \left(\omega t-\frac{x}{\delta}\right)
$$

$$
=\frac{K_{0}^{2}}{\sigma \delta} e^{-\frac{2 x}{\delta}} \cos \left(\omega t-\frac{x}{\delta}\right)\left[\cos \left(\omega t-\frac{x}{\delta}\right)-\sin \left(\omega t-\frac{x}{\delta}\right)\right]
$$

$\bar{S}=0, x<0$

## Final Exam 1995 Solutions

## Problem 1



Figure 13: A magnetic circuit
The magnetic circuit shown above is modeled as being infinitely permeable except for the three thin air-gaps, where $\mu=\mu_{0}$. These thin gaps are narrow enough that fringing fields can be ignored. The $N$ turn coil is driven by the voltage source $v(t)=V_{0} \cos \omega t$.
(A) Determine the self-inductance $L(x)$ of the $N$ turn coil.

## Solution:

$$
\begin{aligned}
& H_{g} g+H_{x} x=N i \\
& \mu_{0} H_{x} b d=2 \mu_{0} H_{g} a d \Rightarrow H_{g}=\frac{H_{x} b}{2 a} \\
& H_{x}\left[x+\frac{g b}{2 a}\right]=N i \Rightarrow H_{x}=\frac{N i}{\left[x+\frac{g b}{2 a}\right]} \\
& V_{0} \cos \omega t=\frac{d \lambda}{d t} \Rightarrow \lambda=\frac{V_{0}}{\omega} \sin \omega t=N \mu_{0} H_{x} b d=\frac{\mu_{0} b d N^{2} i}{\left[x+\frac{g b}{2 a}\right]}
\end{aligned}
$$

$$
L(x)=\frac{\lambda}{i}=\frac{\mu_{0} b d N^{2}}{\left[x+\frac{g b}{2 a}\right]}
$$

(B) Find the total magnetic energy stored in the system as a function of time $t$ in terms of $V_{0}, \omega$, and given geometric and physical parameters.

## Solution:

$$
W_{m}=\frac{1}{2} \frac{\lambda^{2}}{L(x)}=\frac{1}{2} \frac{V_{0}^{2} \sin ^{2} \omega t}{\omega^{2} \mu_{0} b d N^{2}}\left[x+\frac{g b}{2 a}\right]
$$

(C) Determine the magnetic force acting on the movable plunger in the $x$ direction as a function of time $t$ in terms of $V_{0}, \omega$, and given geometric and physical parameters.

## Solution:

$$
f=-\frac{1}{2} \lambda^{2} \frac{d}{d x}\left[\frac{1}{L(x)}\right]=-\frac{V_{0}^{2} \sin ^{2} \omega t}{2 \omega^{2} \mu_{0} b d N^{2}}
$$

## Problem 5

A sphere of magnetic material having radius $R$ is to be magnetized by placing it in a source of uniform magnetic field intensity. The bulk of the sphere has a constant magnetic permeability $\mu$ with zero electrical conductivity, $\sigma=0$. The magnetizable sphere is surrounded by a thin spherical shell of material with thickness $\Delta \ll R$ having electrical conductivity $\sigma$ and magnetic permeability $\mu_{0}$. The field source is switched on at $t=0$ so that $\bar{H}_{0}(t)=H_{0} u(t) \overline{i_{z}}$ where $u(t)$ is the unit step function in time.


Figure 14: A sphere of magnetic material with a non-magnetic conducting coating (Image by MIT OpenCourseWare.)
(A) What is the magnetic field intensity $\bar{H}$ inside the magnetizable sphere for $r<R$ at $t=0^{+}$ and at $t \rightarrow \infty$ ?

## Solution:

$$
\begin{aligned}
& \bar{H}\left(t=0_{+}\right)=0 \quad r<R \\
& t \rightarrow \infty: \bar{H}=-\nabla \chi=-\left[\frac{\partial \chi}{\partial r} \overline{i_{r}}+\frac{1}{r} \frac{\partial \chi}{\partial \theta} \overline{i_{\theta}}\right] \\
& \nabla^{2} \chi=0
\end{aligned}
$$

$$
\begin{aligned}
& \chi= \begin{cases}A r \cos \theta & 0<r<R \\
\left(C r+\frac{D}{r^{2}}\right) \cos \theta & r>R\end{cases} \\
& \lim _{r \rightarrow \infty} \bar{H}=H_{0} \overline{\bar{z}_{z}}=H_{0}\left[\cos \theta \overline{i_{r}}-\sin \theta \overline{i_{\theta}}\right]
\end{aligned} \lim _{r \rightarrow \infty} \chi=-H_{0} z=-H_{0} r \cos \theta\left\{\begin{array}{l}
C=-H_{0} \\
\bar{H}= \begin{cases}-A\left[\cos \theta \overline{i_{r}}-\sin \theta \overline{\theta_{\theta}}\right] \\
-\left[\left(-H_{0}-\frac{2 D}{r^{3}}\right) \cos \theta \overline{i_{r}}-\left(-H_{0}+\frac{D}{r^{3}}\right) \sin \theta \overline{i_{\theta}}\right] & 0<r>R\end{cases} \\
H_{\theta}\left(r=R_{-}\right)=H_{\theta}\left(r=R_{+}\right) \Rightarrow A=-H_{0}+\frac{D}{R^{3}} \\
\mu H_{r}\left(r=R_{-}\right)=\mu_{0} H_{r}\left(r=R_{+}\right) \Rightarrow-\mu A=-\mu_{0}\left(-H_{0}-\frac{2 D}{R^{3}}\right) \\
-\frac{\mu}{\mu_{0}} A=H_{0}+\frac{2 D}{R^{3}} \\
A=-H_{0}+\frac{D}{R^{3}} \\
A=-\frac{3 H_{0}}{2+\frac{\mu}{\mu_{0}}} \\
\bar{H}(r<R, t \rightarrow \infty)=\frac{3 H_{0}}{2+\frac{\mu}{\mu_{0}}} \overline{\bar{i}_{z}}
\end{array}\right.
$$

(B) The radial component of Faraday's law for this problem is:

$$
\nabla \times \bar{E}=-\frac{\partial \bar{B}}{\partial t} \rightarrow \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta E_{\phi}\right)=-\frac{\partial B_{r}}{\partial t}
$$

Because $\Delta \ll R$, the current flow in the conducting spherical shell can be modeled as a surface current, $K_{\phi}(r=R)$. What is the approximate boundary condition at $r=R$ relating the tangential $(\theta)$ component of $\bar{H}$ on either side of the spherical shell to the perpendicular (radial) component of $\bar{B}$ ?

## Solution:

$$
\nabla \times \bar{E}=-\frac{\partial \bar{B}}{\partial t} \Rightarrow \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta E_{\phi}\right)=-\frac{\partial B_{r}}{\partial t}
$$

In spherical shell:

$$
J_{\phi}=\sigma E_{\phi}=\frac{K_{\phi}}{\Delta}=\frac{1}{\Delta}\left[H_{\theta}\left(r=R_{+}\right)-H_{\theta}\left(r=R_{-}\right)\right]
$$

At $r=R$ :

$$
\frac{1}{\sigma \Delta R \sin \theta} \frac{\partial}{\partial \theta}\left[\sin \theta\left(H_{\theta}\left(r=R_{+}\right)-H_{\theta}\left(r=R_{-}\right)\right)\right]=-\frac{\partial B_{r}}{\partial t}
$$

(C) What is the approximate magnetic diffusion time $\tau_{m}$ for this configuration?

Solution:

$$
\begin{aligned}
& H_{\theta}\left(r=R_{+}\right)-H_{\theta}\left(r=R_{-}\right)=\left(-H_{0}+\frac{D}{R^{3}}\right) \sin \theta-A \sin \theta \\
& \mu H_{r}\left(r=R_{-}\right)=\mu_{0} H_{r}\left(r=R_{+}\right) \Rightarrow-\mu A=-\mu_{0}\left(-H_{0}-\frac{2 D}{R^{3}}\right)-\frac{1}{2}\left(\frac{\mu}{\mu_{0}} A+H_{0}\right)=\frac{D}{R^{3}} \\
& H_{\theta}\left(r=R_{+}\right)-H_{\theta}\left(r=R_{-}\right)=\sin \theta\left[-H_{0}-A+\frac{D}{R^{3}}\right]=\sin \theta\left[-H_{0}-A-\frac{1}{2} \frac{\mu}{\mu_{0}} A-\frac{H_{0}}{2}\right] \\
& \frac{1}{\sigma \Delta R \sin \theta} \frac{d}{d \theta}\left[\sin ^{2} \theta\left(-\frac{3 H_{0}}{2}-A\left(\frac{1}{2} \frac{\mu}{\mu_{0}}+1\right)\right)\right]=\mu \frac{\partial A}{\partial t} \cos \theta \\
& \frac{2}{\sigma \Delta R \mu}\left[-\frac{3 H_{0}}{2}-A\left(\frac{1}{2} \frac{\mu}{\mu_{0}}+1\right)\right]=\frac{\partial A}{\partial t} \Rightarrow \frac{d A}{d t}+\frac{2 A}{\sigma \Delta R \mu}\left(\frac{1}{2} \frac{\mu}{\mu_{0}}+1\right)=-\frac{3 H_{0}}{\sigma \Delta R \mu} \\
& \tau_{m}=\frac{\sigma \Delta R \mu}{\left(\frac{\mu}{\mu_{0}}+2\right)}
\end{aligned}
$$

## Final Exam 2000 Solutions

## Problem 1



Figure 15: A magnetic circuit with a gap

The magnetic circuit shown above is modeled as being infinitely permeable except for the gap $g_{1}$ of material with magnetic permeability $\mu_{1}$, and the free space gap partially filled with material with magnetic permeability $\mu_{2}$. The two gaps are sufficiently narrow that fringing fields are negligible. The $N$ turn coil is driven by the voltage source $v(t)=V_{0} \cos \omega t$.
(A) What is the magnetic flux $\lambda$ through the $N$ turn coil in terms of the terminal voltage?

## Solution:

$$
v=V_{0} \cos \omega t=\frac{d \lambda}{d t} \Rightarrow \lambda=\frac{V_{0}}{\omega} \sin \omega t
$$

(B) What are the magnetic fields $H_{1}$ and $H_{2}$ in the two gaps in terms of the magnetic flux, $\lambda$, magnetic permeabilities, and geometric factors?

## Solution:

$$
\begin{aligned}
& \Phi=\frac{\lambda}{N}=\mu_{1} H_{1} a_{1} d=H_{2} d\left(\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right) \\
& H_{1}=\frac{\lambda}{a} N \mu_{1} a_{1} d, H_{2}=\frac{\lambda}{N d\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]}
\end{aligned}
$$

(C) What is the coil current $i$ ?

## Solution:

$$
\begin{aligned}
& H_{1} g_{1}+H_{2} g_{2}=N i=\frac{\lambda g_{1}}{N \mu_{1} a_{1} d}+\frac{\lambda g_{2}}{N d\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]} \\
& i=\frac{\lambda}{N^{2} d}\left[\frac{g_{1}}{\mu_{1} a_{1}}+\frac{g_{2}}{\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]}\right]
\end{aligned}
$$

(D) What is the self-inductance $L(x)$ of the $N$ turn coil where $x$ is the penetration distance of the material with magnetic permeability $\mu_{2}$ into the free space gap?

## Solution:

$$
L(x)=\frac{\lambda}{i}=\frac{N^{2} d}{\left[\frac{g_{1}}{\mu_{1} a_{1}}+\frac{g_{2}}{\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]}\right]}
$$

(E) What is the magnetic stored energy?

## Solution:

$$
W_{m}=\frac{1}{2} L(x) i^{2}=\frac{1}{2} \frac{\lambda^{2}}{L(x)}
$$

(F) Determine the magnitude and direction of the magnetic force on the movable slab with magnetic permeability $\mu_{2}$.

## Solution:

$$
\begin{aligned}
& f_{x}=\frac{1}{2} i^{2} \frac{d L}{d x}=-\frac{\lambda^{2}}{2} \frac{d}{d x}\left(\frac{1}{L(x)}\right) \\
& \frac{1}{L(x)}=\frac{\left[\frac{g_{1}}{\mu_{1} a_{1}}+\frac{g_{2}}{\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]}\right]}{N^{2} d} \\
& f_{x}=-\frac{\lambda^{2}}{2 N^{2} d} g_{2} \frac{-\left(\mu_{2}-\mu_{0}\right)}{\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]^{2}}=\frac{\lambda^{2} g_{2}}{2 N^{2} d} \frac{\left(\mu_{2}-\mu_{0}\right)}{\left[\mu_{2} x+\mu_{0}\left(a_{2}-x\right)\right]^{2}}
\end{aligned}
$$

## Problem 2



Figure 16: Short circuited parallel plate electrodes

Two parallel plate electrodes of area $A$ in free space are a distance $2 a$ apart and are short circuited together. A third electrode at potential $v$ with respect to the other two electrodes and with negligible thickness is placed at a distance $x$ to the right of the midpoint position of the two short circuited electrodes.
(A) Find the electric fields $E_{1}$ and $E_{2}$ on either side of the middle electrode. Neglect fringing field effects.

## Solution:

$$
E_{1}=-\frac{v}{a+x}, E_{2}=\frac{v}{a-x}
$$

(B) What is the total charge on the middle electrode?

## Solution:

$$
q_{\mathrm{mid}}=\epsilon_{0}\left(E_{2}-E_{1}\right) A=\epsilon_{0} v A\left(\frac{1}{a-x}+\frac{1}{a+x}\right)=\frac{2 \epsilon_{0} v A a}{\left(a^{2}-x^{2}\right)}
$$

(C) What is the capacitance of the middle electrode with respect to the short circuited electrodes?

## Solution:

$$
C=\frac{q_{\mathrm{mid}}}{v}=\frac{2 \epsilon_{0} a A}{a^{2}-x^{2}}
$$

(D) If the voltage $v=v(t)$ and position $x=x(t)$ are functions of time, what is the current $i$ flowing in the short circuit?

## Solution:

$$
i=\epsilon_{0} A \frac{d E_{1}}{d t}=-\epsilon_{0} A\left(\frac{1}{a+x} \frac{d v}{d t}-\frac{v}{(a+x)^{2}} \frac{d x}{d t}\right)=-\frac{\epsilon_{0} A}{(a+x)}\left(\frac{d v}{d t}-\frac{v}{(a+x)} \frac{d x}{d t}\right)
$$

(E) What is the electric force on the middle electrode as a function of $x, v, \epsilon_{o}$, and geometric parameters $a$ and $A$ ?

Solution:

$$
f_{x}=\frac{1}{2} v^{2} \frac{d C}{d x}=\frac{1}{\not 2} v^{2}\left(\not 2 \epsilon_{0} a A\right)\left(-\frac{1(-2 x)}{\left(a^{2}-x^{2}\right)^{2}}\right)=\frac{2 \epsilon_{0} a A x v^{2}}{\left(a^{2}-x^{2}\right)^{2}}
$$

## Problem 4



Figure 17: An infinitely long surface charged cylinder
An infinitely long cylinder with dielectric permittivity $\epsilon$ and ohmic conductivity $\sigma$ has outer radius $R_{2}$ and free space hole of radius $R_{1}$. The cylinder is surrounded by free space for $r>R_{2}$. At time $t=0$ a uniform surface charge distribution is placed at $r=R_{1}$ so that $\sigma_{f}\left(r=R_{1}, t=0\right)=\sigma_{f_{0}}$. At time $t=0$ the free surface charge distribution at $r=R_{2}$ is zero.
(A) What is the electric field in the regions $r<R_{1}, R_{1}<r<R_{2}$ and $r>R_{2}$ at time $t=0$ ?

Solution: At $t=0$ :

$$
E_{r}= \begin{cases}0 & r<R_{1} \\ \frac{\sigma_{f_{0}} 2 \pi R_{1}}{2 \pi r \epsilon} & R_{1}<r<R_{2} \\ \frac{\sigma_{f_{0}} 2 \pi R_{1}}{2 \hbar r \epsilon_{0}} & r>R_{2}\end{cases}
$$

(B) Find the electric field in the regions $r<R_{1}, R_{1}<r<R_{2}$, and $r>R_{2}$ as a function of time.

Solution:

$$
\begin{aligned}
& \sigma E_{r}\left(r=R_{1+}\right)+\epsilon \frac{\partial E_{r}\left(r=R_{1+}\right)}{\partial t}=0 \\
& E_{r}\left(r=R_{1+}, t\right)=E_{r}\left(r=R_{1+}, t=0\right) e^{-\frac{t}{\tau}} ; \tau=\frac{\epsilon}{\sigma} \\
& \sigma_{f}\left(r=R_{1}\right)=\epsilon E_{r}\left(r=R_{1+}, t\right)=\epsilon E_{r}\left(r=R_{1+}, t=0\right) e^{-\frac{t}{\tau}} \\
& =\sigma_{f_{0}} e^{-\frac{t}{\tau}}
\end{aligned} \quad \begin{aligned}
& E_{r}(r, t)= \begin{cases}0 & r<R_{1} \\
\frac{\sigma_{f_{0}} R_{1}}{\epsilon r} e^{-\frac{t}{\tau}} & R_{1}<r<R_{2} \\
\frac{\sigma_{f_{0} R_{1}}}{\epsilon_{0} r} & r>R_{2}\end{cases}
\end{aligned}
$$

(C) Find the free surface charge distributions as a function of time at $r=R_{1}$ and $r=R_{2}$.

Solution:

$$
\begin{aligned}
& \sigma_{f}\left(r=R_{1}, t\right)=\sigma_{f_{0}} e^{-\frac{t}{\tau}} \\
& \begin{aligned}
&-\sigma E_{r}\left(r=R_{2-}, t\right)+\frac{\partial \sigma_{f}\left(r=R_{2}, t\right)}{\partial t}=0 \\
& \begin{aligned}
\frac{\partial \sigma_{f}\left(r=R_{2}, t\right)}{\partial t}= & +\sigma E_{r}\left(r=R_{2-}, t\right)=+\frac{\sigma}{\epsilon} \frac{\sigma_{f_{0}}}{R_{2}} R_{1} e^{-\frac{t}{\tau}} \\
\sigma_{f}\left(r=R_{2}, t\right) & =+\frac{\sigma}{\epsilon} \frac{\sigma_{f_{0}} R_{1}}{R_{2}}(-\tau) e^{\frac{t}{\tau}}+C \\
& =\frac{\sigma}{\notin} \frac{\sigma_{f_{0}} R_{1}}{R_{2}}\left(-\frac{\notin}{\varnothing}\right) e^{-\frac{t}{\tau}}+C \\
& =\frac{-\sigma_{f_{0}} R_{1}}{R_{2}} e^{-\frac{t}{\tau}}+C \\
\sigma_{f}\left(r=R_{2}, t=0\right) & =0=\frac{-\sigma_{f_{0}} R_{1}}{R_{2}}+C=0 \Rightarrow C=\frac{\sigma_{f_{0}} R_{1}}{R_{2}} \\
\sigma_{f}\left(r=R_{2}, t\right) & =\frac{\sigma_{f_{0} R_{1}}^{R_{2}}\left(1-e^{-t / \tau}\right)}{}
\end{aligned} .
\end{aligned} .
\end{aligned}
$$

Another Way:

$$
\begin{aligned}
\sigma_{f}\left(r=R_{2}, t\right) & =\epsilon_{0} E_{r}\left(r=R_{2+}, t\right)-\epsilon E_{r}\left(r=R_{2-}, t\right) \\
& =\frac{\sigma_{f_{0}} R_{1}}{R_{2}}-\frac{\sigma_{f_{0}} R_{1}}{R_{2}} e^{-\frac{t}{\tau}} \\
& =\frac{\sigma_{f_{0}} R_{1}}{R_{2}}\left(1-e^{-\frac{t}{\tau}}\right)
\end{aligned}
$$

Another way:

$$
\begin{aligned}
& \sigma_{f}\left(r=R_{1}, t\right) 2 \pi R_{1}+\sigma_{f}\left(r=R_{2}, t\right) 2 \pi R_{2}=\sigma_{f_{0}}\left(2 \pi R_{1}\right) \\
& \begin{aligned}
\sigma_{f}\left(r=R_{2}, t\right) & =\frac{\sigma_{f_{0}} R_{1}}{R_{2}}-\sigma_{f}\left(r=R_{1}, t\right) \frac{R_{1}}{R_{2}} \\
& =\frac{\sigma_{f_{0}} R_{1}}{R_{2}}\left(1-e^{-\frac{t}{\tau}}\right)
\end{aligned}
\end{aligned}
$$

## Problem 5



Figure 18: A surface current sheet at $x=0$ (Image by MIT OpenCourseWare.)

A $z$ directed surface current sheet of infinite extent in the $y$ and $z$ directions is located at $x=0$ and varies with coordinate $y$ as $\bar{K}(x=0, y)=\overline{i_{z}} K_{0} \cos k y$. This current sheet is located at the $x=0$ interface separating a material of infinite magnetic permeability $(\mu \rightarrow \infty)$ for $x<0$ and free space for $0<x<s$. At $x=s$ there is another material of infinite extent for $x>s$ with infinite ohmic conductivity $(\sigma \rightarrow \infty)$. There is no variation with the $z$ coordinates and free space for $0<x<s$ is perfectly insulating $(\sigma=0)$.
(A) What are the boundary conditions on the magnetic field $\bar{H}(x, y)$ at $x=0$ and $x=s$ ?

## Solution:

$$
\begin{aligned}
& H_{y}\left(x=0_{+}\right)=K_{o} \cos k y \\
& H_{x}\left(x=s_{-}\right)=0
\end{aligned}
$$

(B) Find the magnetic field $\bar{H}(x, y)$ everywhere.

## Solution:

$$
\chi(x, y)=\sin k y\left(A e^{-k x}+C e^{+k x}\right) \quad 0<x<s
$$

$$
\begin{aligned}
& \bar{H}=-\nabla \chi= \begin{cases}0 & x<0 \\
0 & x>s \\
-\left[-k A e^{-k x}+k C e^{+k x}\right] \sin k y \overline{\bar{x}_{x}}-k \cos k y\left[A e^{k x}+C e^{+k x}\right] \overline{\bar{y}_{y}} & 0<x<s\end{cases} \\
& H_{x}\left(x=s_{-}\right)=0 \Rightarrow-k A e^{-k s}+k C e^{k s}=0 \\
& H_{y}\left(x=0_{+}\right)=K_{0} \cos k y=-k \cos k y(A+C) \\
& A+C=-\frac{K_{0}}{k} \\
& A=C e^{2 k s} \Rightarrow C\left(1+e^{2 k s}\right)=-\frac{K_{0}}{k} \\
& C=-\frac{\frac{K_{0}}{k}}{\left(1+e^{2 k s}\right)} \\
& A=-\frac{K_{0} e^{2 k s}}{k\left(1+e^{2 k s}\right)} \\
& \bar{H}= \begin{cases}0 & x<0 \\
0 & \frac{K_{0}}{\left(1+e^{2 k s}\right)}\left[\sin (k y)\left(e^{-k x} e^{2 k s}-e^{k x}\right) \overline{i_{x}}-\cos (k y)\left(e^{-k x} e^{2 k s}+e^{k x}\right) \overline{i_{y}}\right] \\
0<x<s\end{cases} \\
& 0<x<s \\
& \bar{H}=-\frac{2 K_{0} e^{k s}}{\left(1+e^{2 k s}\right)}\left[\sin (k y)(-\sinh (k(x-s))) \overline{i_{x}}-\cos (k y) \cosh (k(x-s)) \overline{i_{y}}\right]
\end{aligned}
$$

Check:

$$
\begin{aligned}
& H_{x}(x=s)=0 \\
& H_{y}(x=0)=K_{0} \cos (k y)
\end{aligned}
$$

(C) What is the surface current on the $x=s$ surface?

## Solution:

$$
K_{z}(x=s)=-H_{y}(x=s)=\frac{K_{0} \cos (k y)}{\cosh (k s)}
$$

